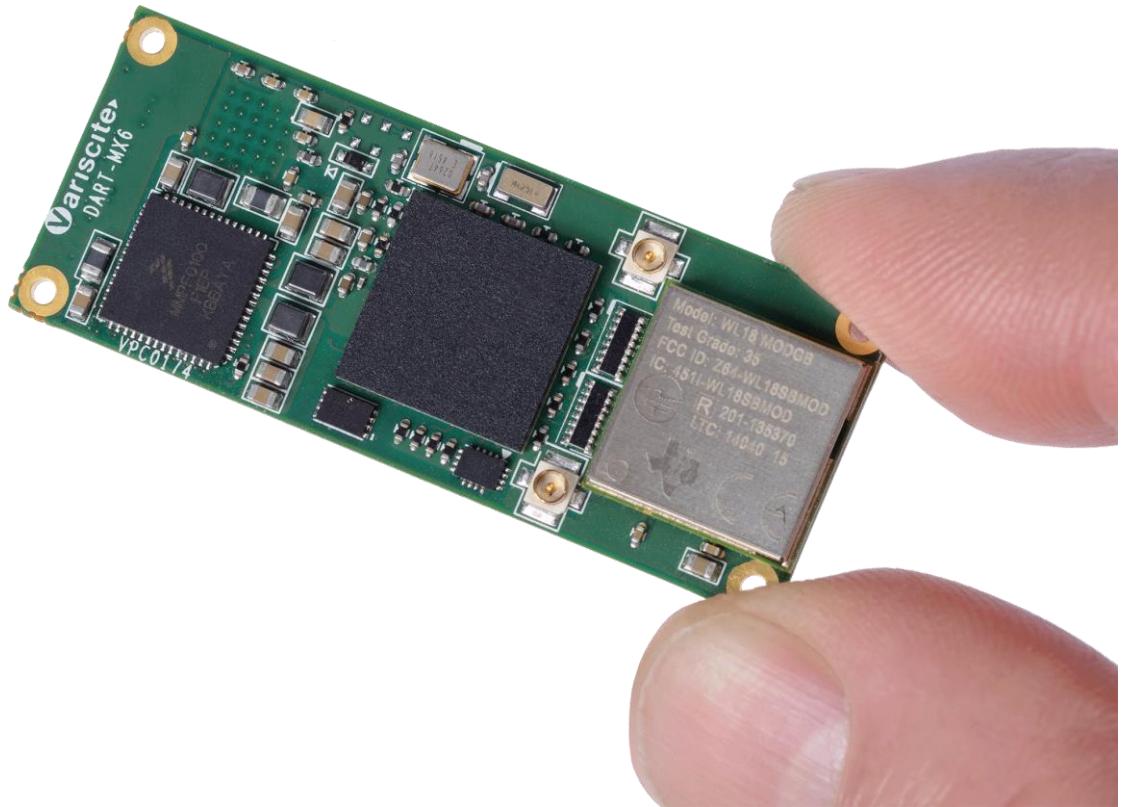




VARISCITE LTD.

DART-MX6 v1.1 Datasheet

Freescale i.MX6™ - based System-on-Module



VARISCITE LTD.

DART-MX6 Datasheet

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|----------|------------|---------|
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| | | |

DART-MX6 SYSTEM ON MODULE

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|--|----|
| Document Revision History | 3 |
| 1. Overview..... | 5 |
| 1.1. General Information | 5 |
| 1.2. Feature Summary | 6 |
| 1.3. Block Diagram..... | 7 |
| 2. Main Hardware Components | 8 |
| 2.1. Freescale i.MX6 | 8 |
| 2.2. Memory | 13 |
| 2.3. TLV320AIC3106 Audio | 13 |
| 2.4. Wi-Fi + BT..... | 13 |
| 2.5. PMIC..... | 14 |
| 3. External Connectors..... | 14 |
| 3.1. DART-MX6 Connector Pin-out | 15 |
| 3.2. SO-DIMM 200 Pin Mux | 21 |
| 4. SOM's interfaces..... | 26 |
| 4.1. Display Interfaces | 26 |
| 4.2. Camera Interfaces | 29 |
| 4.3. Gigabit Ethernet | 31 |
| 4.4. Wi-Fi & Bluetooth..... | 31 |
| 4.5. USB Host 2.0 | 32 |
| 4.6. USB 2.0 OTG | 32 |
| 4.7. MMC/SD/SDIO..... | 32 |
| 4.8. Audio..... | 33 |
| 4.9. UART Interfaces | 34 |
| 4.10. Flexible Controller Area Network (FLEXCAN) | 35 |
| 4.11. SPI..... | 36 |
| 4.12. PCIe..... | 37 |
| 4.13. I ² C..... | 38 |
| 4.14. JTAG..... | 38 |
| 4.15. General Purpose IOs | 39 |
| 4.16. General System Control..... | 39 |
| 4.17. Power..... | 40 |
| 5. Absolute Maximum Characteristics | 41 |
| 6. Operational Characteristics | 41 |
| 6.1. Power supplies | 41 |
| 6.2. Power Consumption | 41 |
| 7. DC Electrical Characteristics | 41 |
| 8. Environmental Specifications | 42 |
| 9. Mechanical Drawings..... | 42 |
| 10. Legal Notice | 43 |
| 11. Warranty Terms..... | 44 |
| 12. Contact Information | 45 |

1. Overview

1.1. General Information

The DART-MX6 is a high performance System-on-Module. It provides an ideal building block that easily integrates with a wide range of target markets requiring rich multimedia functionality, powerful graphics and video capabilities, as well as high-processing power. Compact, cost effective and with low power consumption, DART-MX6 secures an Intel Atom performance level.

Supporting products:

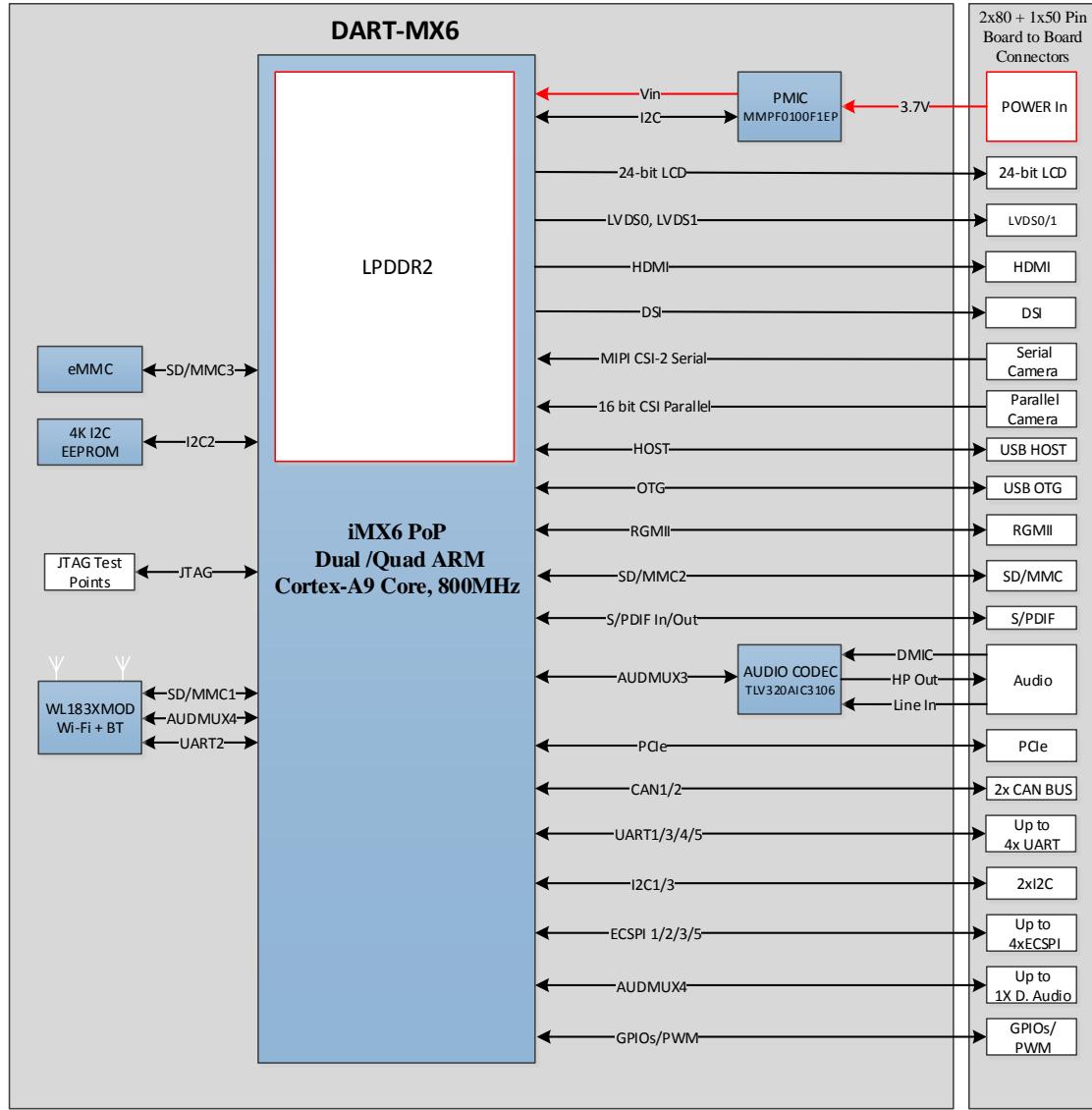
- VAR-DT6CustomBoard – evaluation board
 - ✓ Carrier -Board, compatible with DART-MX6
 - ✓ Schematics
- O.S support
 - ✓ Linux BSP
 - ✓ Windows Embedded Compact 7
 - ✓ Android

Contact Variscite support services for further information: <mailto:support@variscite.com>.

1.2. Feature Summary

- Freescale i.MX6 series SoC (Dual /Quad ARM® Cortex™-A9 Core, 800Mhz)
- Up to 1GB LPDDR2 RAM
- Up to 64GB eMMC storage
- 24 bit Parallel LCD interface
- 2 x LVDS display interface
- HDMI V1.4 interface
- 1 x MIPI DSI
- Parallel & serial camera interface
- TI WiLink8 2.4/5GHz WLAN (802.11 a/b/g/n) / BT-BLE with optional MIMO
- 1 x USB 2.0 host, 1 x OTG
- 10/100/1000 Mbit/s Ethernet RGMII Interface
- 1 x SD/MMC
- Serial interfaces (SPI , I2C, UART, I2S, SPDIF)
- PCIe
- CAN Bus
- Stereo line-In / headphones out
- Digital microphone
- Single 3.7 V power supply
- 50mm x 20mm, 2x80 + 1x50 pin Board to Board Connectors

1.3. Block Diagram



2. Main Hardware Components

This section summarizes the main hardware building blocks of the DART-MX6

2.1. Freescale i.MX6

2.1.1. Overview

The i.MX6Dual and i.MX6 Quad PoP processors represent Freescale Semiconductor's latest achievement in integrated multimedia applications processors, optimized for lowest power consumption. The processors feature Freescale's advanced implementation of the quad ARM™ Cortex-A9 core, which operates at speeds of up to 800 MHz. They include 2D and 3D graphics processors, 3D 1080p video processing and integrated power management. Each processor provides a 2X32-bit LPDDR2-800 memory interface and a number of other interfaces such as WLAN, Bluetooth™, GPS, hard drive, displays, and camera sensors.

2.1.2. i.MX6 Block Diagram

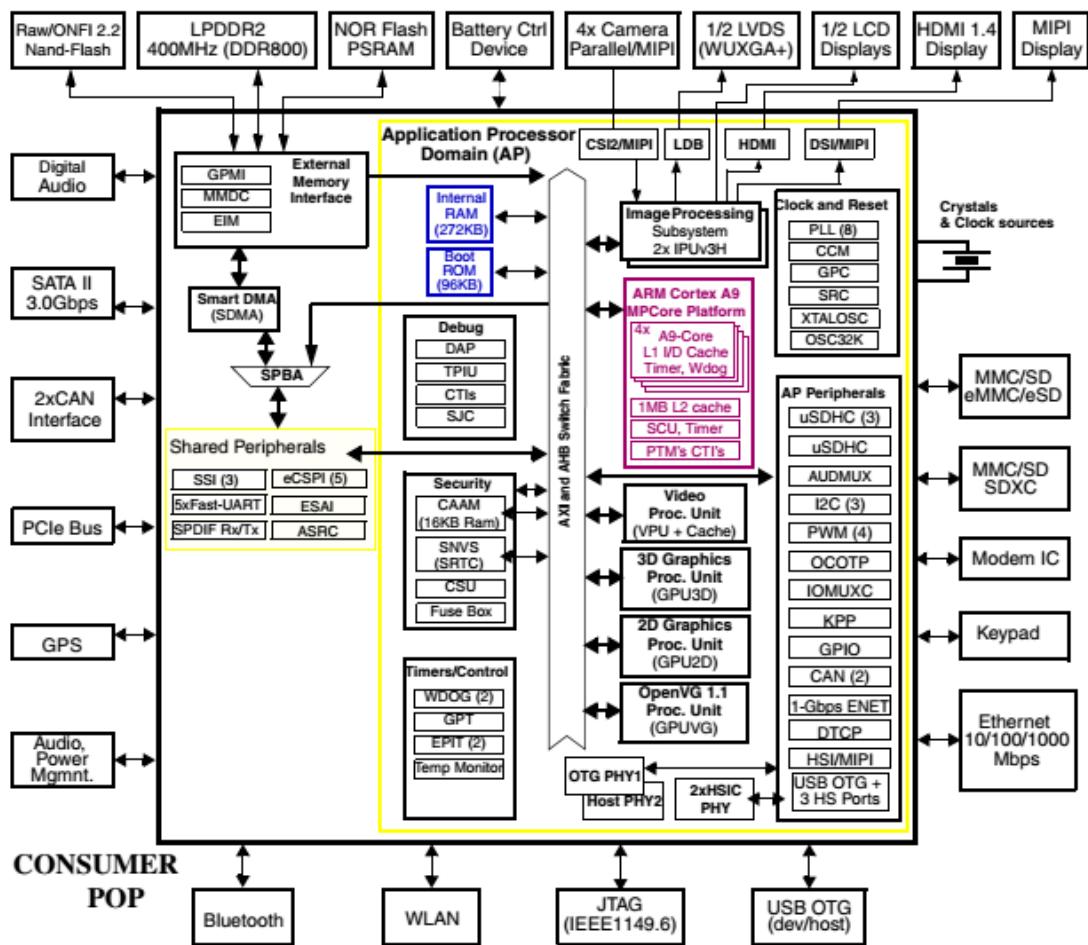


Figure 2. i.MX 6Dual/6Quad Consumer Grade System Block Diagram

2.1.3. CPU Platform

The i.MX6 Dual / Quad Application Processor (AP) is based on the ARM Cortex-A9 MPCore™ Platform, which has the following features:

- ARM Cortex A9 MPCore™ Dual or Quad core CPU configurations (with TrustZone)
- Symmetric CPU configuration where each CPU includes:
 - 32 Kbyte L1 Instruction Cache
 - 32 Kbyte L1 Data Cache
 - Private Timer and Watchdog
 - Cortex-A9 NEON MPE (Media Processing Engine) Co-processor.
- The ARM Cortex A9 MPCore™ complex includes:
 - General Interrupt Controller (GIC) with 128 interrupt support
 - Global Timer
 - Snoop Control Unit (SCU)
 - 1 Megabyte unified L2 cache shared by all CPU cores (Dual or Quad)
 - Two Master AXI (64-bit) bus interfaces output of L2 cache
 - NEON MPE coprocessor
 - SIMD Media Processing Architecture
 - NEON register file with 32x64-bit general-purpose registers
 - NEON Integer execute pipeline (ALU, Shift, MAC)
 - NEON dual, single-precision floating point execute pipeline (FADD, FMUL)
 - NEON load/store and permute pipeline External
 - Supports single and double-precision add, subtract, multiply, divide, multiply and accumulate, and square root operations as described in the ARM VFPv3 architecture.
 - Provides conversions between 16-bit, 32-bit and 64-bit floating-point formats and ARM integer word formats.

2.1.4. Memory Interfaces

The memory system consists of the following components:

- Level 1 Cache—32 KB Instruction, 32 KB Data cache per core
- Level 2 Cache—Unified instruction and data (1 MByte)
- On-Chip Memory:
 - Boot ROM, including HAB (96 KB)
 - Internal multimedia / shared, fast access RAM (OCRAM, 256 KB)
 - Secure/non-secure RAM (16 KB)
- External memory interfaces:
 - 2×32-bit, LPDDR2-800 channels supporting DDR interleaving mode
 - 8-bit NAND-Flash, including support for Raw MLC/SLC, 2 KB, 4 KB, and 8 KB page size,
 - BA-NAND, PBA-NAND, LBA-NAND, OneNAND™ and others. BCH ECC up to 40 bit.
 - 16-bit NOR Flash. All WEIMv2 pins are muxed on other interfaces.
 - 16-bit PSRAM, Cellular RAM

2.1.5. DMA engine

The SDMA is multi-channel flexible DMA engine. It helps in maximizing system performance by off-loading the various cores in dynamic data routing. It has the following features:

- Powered by a 16-bit Instruction-Set micro-RISC engine
- Multi-channel DMA supporting up to 32 time-division multiplexed DMA channels
- 48 events with total flexibility to trigger any combination of channels
- Memory accesses including linear, FIFO, and 2D addressing
- Shared peripherals between ARM and SDMA
- Very fast Context-Switching with 2-level priority based preemptive multi-tasking
- DMA units with auto-flush and prefetch capability
- Flexible address management for DMA transfers (increment, decrement, and no address changes on source and destination address)
- DMA ports can handle unit-directional and bi-directional flows (copy mode)
- Up to 8-word buffer for configurable burst transfers
- Support of byte-swapping and CRC calculations
- Library of Scripts and API is available

2.1.6. Display Subsystem

The i.MX6Dual/6Quad video graphics subsystem consists of the following dedicated modules:

- Video Processing Unit (VPU): a multi-standard high performance video/image CODEC
- Three Graphics Processing Units (GPUs):
 - 3D GPU: accelerating the generation of 3D graphics (OpenGL/ES) and vector graphics (OpenVG)
 - 2D GPU: acceleration the generation of 2D graphics (BitBLT).
 - OpenVG: acceleration of vector graphics (OpenVG).
- Two (identical) Image Processing Units (IPUs): providing connectivity to cameras and displays, related processing, synchronization and control.
- Display interface bridges: providing optional translation from the digital display interface supported by the IPU to other interfaces:
 - LVDS bridge (LDB): providing up to two LVDS interfaces
 - HDMI transmitter
 - MIPI/DSI transmitter
- MIPI/CSI-2 receiver
- Two (identical) Display Content Integrity Checker (DCIC) are used to authenticate sensitive displayed data.
- A Video Data Order Adapter (VDOA): used to re-order video data from the "tiled" order used by the VPU to the conventional raster-scan order needed by the IPU.

2.1.7. MIPI - Camera Serial Interface Host Controller

The MIPI CSI-2 Host Controller supports the following features:

- Compliant with MIPI Alliance Standard for Camera Serial Interface 2 (CSI-2), Version 1.00

- Optional support for Camera Control Interface (CCI) through the use of DesignWare Core (DW_apb_i2c)
- Interface with MIPI D-PHY following PHY Protocol Interface (PPI), as defined in MIPI Alliance Specification for D-PHY, Version 1.00.00 - 14 May 2009
- Supports up to 4 D-PHY Rx Data Lanes
- Dynamically configurable multi-lane merging
- Long and Short packet decoding
- Timing accurate signaling of Frame and Line synchronization packets; Support for several frame formats such as:
 - General Frame or Digital Interlaced Video with or without accurate sync timing
 - Data type (Packet or Frame level) and Virtual Channel interleaving
- 32-bit Image Data Interface delivering data formatted as recommended in CSI-2 Specification
- Supports all primary and secondary data formats:
 - RGB, YUV and RAW color space definitions
 - From 24-bit down to 6-bit per pixel
 - Generic or user-defined byte-based data types
 - Error detection and correction
 - PHY level
 - Packet level
 - Line level
 - Frame level

2.1.8. 2D and 3D Graphics Processing Unit (GPU)

The GPU2D module has two independent sub-modules: R2D and V2D GPUs. Both GPU were designed to display on a variety of consumer devices. Addressable screen sizes range from small displays featured on cell phones to large 1080p high definition displays.

The GPU2D cores provide powerful graphics at low power consumption, utilizing the smallest silicon footprints. Dynamic power consumption is minimized by extensive use of localized clock gating.

Hardware acceleration is brought to numerous 2D and VG applications including graphical user interfaces (GUI), menu displays, flash animation and gaming.

The GPU3D is a high-performance core that delivers hardware acceleration for 3D graphics display. Addressable screen sizes range from the smallest cell phones to HD 1080p displays. It provides high performance, high quality graphics, low power consumption and the smallest silicon footprint.

GPU3D accelerates numerous 3D graphics applications, including Graphical User Interfaces (GUI), menu displays, flash animation, and gaming. This module supports the following graphics APIs:

- OpenGL ES 2.0
- OpenGL ES 1.1
- OpenVG 1.1
- EGL 1.4
- DirectX 11_9_3
- OpenGL 2.1 and 3.0
- OpenCL 1.1 E

2.1.9. Audio Back End

The AUDMUX provides flexible, programmable routing of the serial interfaces (SSI1 or SSI2) to and from off-chip devices. The AUDMUX routes audio data (and even splices together multiple time-multiplexed audio streams) but does not decode or process audio data itself. The AUDMUX is controlled by the ARM but can route data even when the ARM is in a low-power mode.

The ESAI (Enhanced Serial Audio Interface) provides a full-duplex serial port for serial communication with a variety of serial devices, including industry-standard codecs, SPDIF transceivers, and other processors. The ESAI consists of independent transmitter and receiver sections, each section with its own clock generator. The ESAI is connected to the IOMUX and to the ESAI_BIFIFO module.

The ESAI_BIFIFO (ESAI Bus Interface and FIFO) is the interface between the ESAI module and the shared peripheral bus. It contains the FIFOs used to buffer data to and from the ESAI, as well as providing the data word alignment and padding necessary to match the 24-bit data bus of the ESAI to the 32-bit data bus of the shared peripheral bus.

The SPDIF (Sony/Philips Digital Interface) audio module is a stereo transceiver that allows the processor to receive and transmit digital audio over it. The SPDIF receiver section includes a frequency measurement block that allows the precise measurement of incoming sampling frequency. A recovered clock is provided by the SPDIF receiver section and may be used to drive both internal and external components in the system. The SPDIF is connected to the shared peripheral bus.

The ASRC (Asynchronous Sample Rate Converter) converts the sampling rate of a signal associated to an input clock into a signal associated to a different output clock. The ASRC supports concurrent sample rate conversions of up to 10 channels of over 120dB THD+N. The sample rate conversion of each channel is associated to a pair of incoming and outgoing sampling rates. The ASRC supports up to three sampling rate pairs. The ASRC is connected to the shared peripheral bus.

2.1.10. 10/100/1000 Ethernet Controller

The MAC-NET core, in conjunction with a 10/100/1000 MAC, implements layer 3 network acceleration functions. These functions are designed to accelerate the processing of various common networking protocols, such as IP, TCP, UDP and ICMP, providing wire speed services to client applications. The MAC operation is fully programmable and can be used in NIC (Network Interface Card), bridging, or switching applications. The core implements the remote network monitoring (RMON) counters according to IETF RFC 2819. The core also implements a hardware acceleration block to optimize the performance of network controllers providing IP and TCP, UDP, ICMP protocol services. The acceleration block performs critical functions in hardware, which are typically implemented with large software overhead. The core implements programmable embedded FIFOs that can provide buffering on the receive path for loss-less flow control .Advanced power management features are available with magic packet detection and programmable power-down modes.

2.2. Memory

2.2.1. RAM

The DART-MX6 is available with up to 1 GB of LPDDR2 memory.

2.2.2. Non-volatile Storage Memory

- eMMC: Up to 64GB of storage.

2.3. TLV320AIC3106 Audio

The Texas Instrument's TLV320AIC3106 is a low-power, highly integrated stereo audio codec with stereo headphone amplifier, as well as multiple inputs and outputs programmable in single-ended or fully differential configurations. Extensive register-based power control is included, enabling stereo 48-kHz DAC playback as low as 15mW. The DART-MX6 exposes the following interface of the TLV320AIC3106:

- Headphone
- Line-in
- Digital microphone

2.4. Wi-Fi + BT

The DART-MX6 contains TI's WL183xMOD WiLink, a high performance 2.4/5 GHz IEEE 802.11 a/b/g/n Bluetooth 4.0/BLE radio module with optional Dual Band and MIMO support.

The modules support improved performance over WiFi in bit rates reaching 100Mbps (UDP) and 80Mbps (TCP).

The module realizes the necessary PHY/MAC layers to support WLAN applications in conjunction with a host processor over a SDIO interface.

The module also provides a Bluetooth platform through the HCI transport layer. Both WLAN and Bluetooth share the same antenna port.

- IEEE 802.11 b,g,n or Dual Band 2.4/5GHz 802.11 a/b/g/n with optional MIMO
- Bluetooth 4.0/BLE
- U.FL connectors for external antennas
- Integrated band-pass filter
- Operating Temperature Range:
Dual Band 2.4/5GHz Modules: -40 to +85
2.4GHz Modules: -20 to +70

2.5. PMIC

The DART-MX6 features Freescale's PMPF0100 as a Power Management Integrated circuit (PMIC) designed specifically for use with Freescale's i.MX6 series of application processors. The PMPF0100 regulates all power rails required on SoM from a single 3.7 V power supply. The PMIC is fully programmable via the I2C interface and associated register map. Additional communication is provided by direct logic interfacing including interrupt, watchdog and reset.

3. External Connectors

The DART-MX6 exposes three low profile connectors. Two 80 pin and one 50 pin Board to Board connectors. The recommended mating connectors for Customboard interfacing are:

1. 50 Pin: DF40C-50DS-0.4V(51)
2. 80 Pin: DF40C-80DS-0.4V(51)

Pin#:

Pin number on the SO-DIMM200 connector

Pin Name:

Default DART-MX6 pin name

Type:

Pin type & direction:

- I – In
- O – Out
- DS – Differential Signal
- A – Analog
- Power – Power Pin

Pin Group:

Pin functionality group

i.MX6 Ball:

Ball number

Mode (Tables 3.2 & 3.4):

Pin mux mode option

3.1. DART-MX6 Connector Pin-out

| J1 | | | | | | |
|-------|----------------|-------|------------------------------|-----------|------------|--|
| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball | |
| 1 | HPOUT | AO | | | | |
| 2 | GND | POWER | Digital GND | | | |
| 3 | HPROUT | AO | | | | |
| 4 | LINEIN1_RP | AI | | | | |
| 5 | AGND | POWER | Audio GND | | | |
| 6 | LINEIN1_LP | AI | | | | |
| 7 | GND | POWER | Digital GND | | | |
| 8 | AGND | POWER | Audio GND | | | |
| 9 | ECSPI1_MISO | IO | Configurable SPI | GPIO4[8] | Y7 | |
| 10 | GND | POWER | Digital GND | | | |
| 11 | ECSPI1_MOSI | IO | Configurable SPI | GPIO4[7] | AB7 | |
| 12 | DMIC_DATA | I | Digital microphone interface | | | |
| 13 | ECSPI1_CLK | IO | Configurable SPI | GPIO4[6] | AB6 | |
| 14 | DMIC_CLK | O | Digital microphone interface | | | |
| 15 | ECSPI1_CS1 | IO | Configurable SPI | GPIO4[10] | AD7 | |
| 16 | HDMI_DDCCEC | IO | HDMI | | R2 | |
| 17 | GND | POWER | Digital GND | | | |
| 18 | CAN2_TX_OTG_OC | IO | FlexCAN-2 | GPIO4[14] | AF1 | |
| 19 | MX6_ONOFF | I | Power On/Off | | A13 | |
| 20 | CAN2_RX | I | FlexCAN-2 | GPIO4[15] | AC7 | |
| 21 | CAN1_TX | O | FlexCAN-1 | GPIO1[7] | AC1 | |
| 22 | HDMI_HPD | I | HDMI | | R1 | |
| 23 | CAN1_RX | I | FlexCAN-1 | GPIO1[8] | V7 | |
| 24 | GND | POWER | Digital GND | | | |
| 25 | GPIO1[28] | IO | General purpose | GPIO1[28] | AG24 | |
| 26 | VBAT | POWER | 3.7 V power supply IN | | | |
| 27 | VBAT | POWER | 3.7 V power supply IN | | | |
| 28 | VBAT | POWER | 3.7 V power supply IN | | | |
| 29 | VBAT | POWER | 3.7 V power supply IN | | | |
| 30 | VBAT | POWER | 3.7 V power supply IN | | | |
| 31 | VBAT | POWER | 3.7 V power supply IN | | | |
| 32 | VBAT | POWER | 3.7 V power supply IN | | | |
| 33 | VBAT | POWER | 3.7 V power supply IN | | | |
| 34 | GND | POWER | Digital GND | | | |
| 35 | GND | POWER | Digital GND | | | |
| 36 | UART1_RTS | I | UART1 port | GPIO3[20] | J23 | |

| J1 | | | | | |
|-------|-----------|-------|--------------------------------|-----------|------------|
| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball |
| 37 | UART3_RTS | I | UART3 port ^{[1], [2]} | GPIO2[31] | K27 |
| 38 | UART1_CTS | O | UART1 port | GPIO3[19] | J29 |
| 39 | UART3_CTS | O | UART3 port | GPIO3[23] | K24 |
| 40 | UART1_RXD | I | UART1 port | GPIO5[29] | V1 |
| 41 | UART3_RXD | I | UART3 port | GPIO3[25] | L28 |
| 42 | UART1_TXD | O | UART1 port | GPIO5[28] | W3 |
| 43 | UART3_TXD | O | UART3 port | GPIO3[24] | L29 |
| 44 | GPIO4_11 | IO | General purpose | GPIO4[11] | AF2 |
| 45 | GPIO1_6 | IO | General purpose | GPIO1[6] | AC6 |
| 46 | GETH_RST | O | Gigabit Ethernet | GPIO1[25] | AG23 |
| 47 | PWM2 | IO | Pulse width modulation 2 | GPIO1[1] | AA6 |
| 48 | POR_B | I | Reset | | F13 |
| 49 | GND | POWER | Digital GND | | |
| 50 | GND | POWER | Digital GND | | |

| J2 | | | | | |
|-------|--------------|-------|-------------------------|-----------|------------|
| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball |
| 1 | CSI_D0P | DS | Camera serial interface | | C1 |
| 2 | SW4_1V8 | POWER | PMIC 1.8V output | | |
| 3 | CSI_D0M | DS | Camera serial interface | | C2 |
| 4 | CSI_D3M | DS | Camera serial interface | | G2 |
| 5 | CSI_D1M | DS | Camera serial interface | | D1 |
| 6 | CSI_D3P | DS | Camera serial interface | | G1 |
| 7 | CSI_D1P | DS | Camera serial interface | | D2 |
| 8 | CSI_CLK0P | DS | Camera serial interface | | E1 |
| 9 | CSI_D2P | DS | Camera serial interface | | F2 |
| 10 | CSI_CLK0M | DS | Camera serial interface | | E2 |
| 11 | CSI_D2M | DS | Camera serial interface | | F1 |
| 12 | USB_H1_VBUS | I | USB 2.0 5V indication | | C11 |
| 13 | GPIO1_4 | IO | General purpose | GPIO1_4 | Y6 |
| 14 | USB_OTG_VBUS | I | OTG 5V indication | | G11 |
| 15 | GND | POWER | Digital GND | | |
| 16 | GEN_2V5 | POWER | PMIC 2.5V output | | |
| 17 | GND | POWER | Digital GND | | |
| 18 | USB_H1_OC | I | USB host | GPIO3[30] | N29 |
| 19 | PCIE_TXP | DS | PCI express interface | | B5 |

| J2 | | | | | |
|-------|-------------|-------|--------------------------|-----------|------------|
| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball |
| 20 | GND | POWER | Digital GND | | |
| 21 | PCIE_TXM | DS | PCI express interface | | A5 |
| 22 | USB_HOST_DN | DS | USB host | | B11 |
| 23 | PCIE_RXP | DS | PCI express interface | | A3 |
| 24 | USB_HOST_DP | DS | USB host | | A11 |
| 25 | PCIE_RXM | DS | PCI express interface | | B3 |
| 26 | GND | POWER | Digital GND | | |
| 27 | USB_OTG_DN | DS | USB on-the-go | | B9 |
| 28 | HDMI_CLKP | DS | HDMI | | L2 |
| 29 | USB_OTG_DP | DS | USB on-the-go | | A9 |
| 30 | HDMI_CLKM | DS | HDMI | | L1 |
| 31 | GND | POWER | Digital GND | | |
| 32 | GND | POWER | Digital GND | | |
| 33 | DSI_DOP | DS | Display serial interface | | H1 |
| 34 | DSI_D1M | DS | Display serial interface | | K2 |
| 35 | DSI_D0M | DS | Display serial interface | | H2 |
| 36 | DSI_D1P | DS | Display serial interface | | K1 |
| 37 | DSI_CLK0P | DS | Display serial interface | | J2 |
| 38 | USB_OTG_ID | I | USB on-the-go | GPIO1[24] | AD22 |
| 39 | DSI_CLK0M | DS | Display serial interface | | J1 |
| 40 | CLK1_P | DS | PCIE clock | | B7 |
| 41 | ECSPI1_CS0 | IO | Configurable SPI | GPIO4[9] | AD3 |
| 42 | CLK1_N | DS | PCIE clock | | A7 |
| 43 | GND | POWER | Digital GND | | |
| 44 | HDMI_DOP | DS | HDMI | | M2 |
| 45 | I2C1_SDA | IO | I2C1 interface | GPIO5[26] | W2 |
| 46 | HDMI_D0M | DS | HDMI | | M1 |
| 47 | I2C1_SCL | IO | I2C1 interface | GPIO5[27] | W1 |
| 48 | HDMI_D1P | DS | HDMI | | N2 |
| 49 | I2C3_SDA | IO | I2C3 interface | GPIO7[11] | AB2 |
| 50 | HDMI_D1M | DS | HDMI | | N1 |
| 51 | I2C3_SCL | IO | I2C3 interface | GPIO1[5] | AB3 |
| 52 | GND | POWER | Digital GND | | |
| 53 | GND | POWER | Digital GND | | |
| 54 | HDMI_D2P | DS | HDMI | | P2 |
| 55 | CLKO2 | O | Reference clock out | GPIO1[3] | AE1 |
| 56 | HDMI_D2M | DS | HDMI | | P1 |
| 57 | LVDS0_TX0_N | DS | LVDS0 display bridge | | AG2 |

J2

| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball |
|-------|-------------|-------|----------------------|------|------------|
| 58 | LVDS1_TX0_N | DS | LVDS1 display bridge | | AJ6 |
| 59 | LVDS0_TX0_P | DS | LVDS0 display bridge | | AG1 |
| 60 | LVDS1_TX0_P | DS | LVDS1 display bridge | | AH6 |
| 61 | LVDS0_TX1_N | DS | LVDS0 display bridge | | AH2 |
| 62 | LVDS1_TX1_N | DS | LVDS1 display bridge | | AH7 |
| 63 | LVDS0_TX1_P | DS | LVDS0 display bridge | | AH1 |
| 64 | LVDS1_TX1_P | DS | LVDS1 display bridge | | AJ7 |
| 65 | LVDS0_TX2_N | DS | LVDS0 display bridge | | AH3 |
| 66 | LVDS1_TX2_N | DS | LVDS1 display bridge | | AJ9 |
| 67 | LVDS0_TX2_P | DS | LVDS0 display bridge | | AJ3 |
| 68 | LVDS1_TX2_P | DS | LVDS1 display bridge | | AH9 |
| 69 | GND | POWER | Digital GND | | |
| 70 | GND | POWER | Digital GND | | |
| 71 | LVDS0_TX3_N | DS | LVDS0 display bridge | | AH5 |
| 72 | LVDS1_TX3_N | DS | LVDS1 display bridge | | AJ10 |
| 73 | LVDS0_TX3_P | DS | LVDS0 display bridge | | AJ5 |
| 74 | LVDS1_TX3_P | DS | LVDS1 display bridge | | AH10 |
| 75 | LVDS0_CLK_N | DS | LVDS0 display bridge | | AH4 |
| 76 | LVDS1_CLK_N | DS | LVDS1 display bridge | | AJ8 |
| 77 | LVDS0_CLK_P | DS | LVDS0 display bridge | | AJ4 |
| 78 | LVDS1_CLK_P | DS | LVDS1 display bridge | | AH8 |
| 79 | GND | POWER | Digital GND | | |
| 80 | GND | POWER | Digital GND | | |

J3

| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball |
|-------|------------|------|-----------------|-----------|------------|
| 1 | RGMII_TCLK | O | RGMII Interface | GPIO6[19] | C29 |
| 2 | RGMII_RCLK | I | RGMII Interface | GPIO6[30] | H24 |
| 3 | RGMII_TCTL | O | RGMII Interface | GPIO6[26] | G28 |
| 4 | RGMII_RCTL | I | RGMII Interface | GPIO6[24] | F28 |
| 5 | RGMII_TD0 | O | RGMII Interface | GPIO6[20] | C28 |
| 6 | RGMII_RD0 | I | RGMII Interface | GPIO6[25] | G27 |
| 7 | RGMII_TD1 | O | RGMII Interface | GPIO6[21] | E29 |
| 8 | RGMII_RD1 | I | RGMII Interface | GPIO6[27] | F29 |
| 9 | RGMII_TD2 | O | RGMII Interface | GPIO6[22] | G24 |

J3

| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball |
|-------|----------------------|-------|--|-----------|------------|
| 10 | RGMII_RD2 | I | RGMII Interface | GPIO6[28] | H23 |
| 11 | RGMII_TD3 | O | RGMII Interface | GPIO6[23] | F27 |
| 12 | RGMII_RD3 | I | RGMII Interface | GPIO6[29] | G29 |
| 13 | GND | POWER | Digital GND | | |
| 14 | GND | POWER | Digital GND | | |
| 15 | CSI1_DATA_EN | I | Camera Parallel Interface | GPIO3[10] | Y28 |
| 16 | SD2_CLK | O | SD/MMC and SDXC | GPIO1[10] | E28 |
| 17 | CSI1_HSYNC/BT_CFG2_3 | I | Camera Parallel Interface/Boot Select ^[1] | GPIO3[11] | AE29 |
| 18 | SD2_DATA0 | IO | SD/MMC and SDXC | GPIO1[15] | B29 |
| 19 | CSI1_VSYNC/BT_CFG2_4 | I | Camera Parallel Interface/Boot Select ^[1] | GPIO3[12] | Y27 |
| 20 | SD2_CMD | IO | SD/MMC and SDXC | GPIO1[11] | D29 |
| 21 | CSI1_PIXCLK | I | Camera Parallel Interface | GPIO2[22] | T29 |
| 22 | SD2_DATA2 | IO | SD/MMC and SDXC | GPIO1[13] | B28 |
| 23 | CSI1_DATA4/BT_CFG1_5 | I | Camera Parallel Interface/Boot Select ^[1] | GPIO3[5] | W28 |
| 24 | SD2_DATA1 | IO | SD/MMC and SDXC | GPIO1[14] | F24 |
| 25 | CSI1_DATA5 | I | Camera Parallel Interface | GPIO3[4] | W27 |
| 26 | SD2_DATA3 | IO | SD/MMC and SDXC | GPIO1[12] | F23 |
| 27 | GND | POWER | Digital GND | | |
| 28 | GND | POWER | Digital GND | | |
| 29 | SPDIFIN | I | SPDIF | GPIO3[21] | K29 |
| 30 | CSI1_DATA19 | I | Camera Parallel Interface | GPIO5[4] | N27 |
| 31 | SPDIFOUT | O | SPDIFIN | GPIO3[22] | K28 |
| 32 | CSI1_DATA18 | I | Camera Parallel Interface | GPIO6[6] | N28 |
| 33 | CSI1_DATA8 | I | Camera Parallel Interface | GPIO3[1] | V27 |
| 34 | CSI1_DATA17 | I | Camera Parallel Interface | GPIO2[16] | P28 |
| 35 | CSI1_DATA9 | I | Camera Parallel Interface | GPIO3[0] | V28 |
| 36 | CSI1_DATA16 | I | Camera Parallel Interface | GPIO2[17] | P29 |
| 37 | CSI1_DATA10 | I | Camera Parallel Interface | GPIO2[29] | P24 |
| 38 | CSI1_DATA15 | I | Camera Parallel Interface | GPIO2[18] | R29 |
| 39 | GND | POWER | Digital GND | | |
| 40 | GND | POWER | Digital GND | | |
| 41 | CSI1_DATA11 | I | Camera Parallel Interface | GPIO2[28] | N23 |
| 42 | DISPO_VSYNC | O | LCD Vertical Sync | GPIO4[19] | W24 |
| 43 | CSI1_DATA12 | I | Camera Parallel Interface | GPIO2[21] | N24 |
| 44 | DISPO_DATA_EN | O | LCD Data Enable | GPIO4[17] | AD28 |
| 45 | CSI1_DATA13 | I | Camera Parallel Interface | GPIO2[20] | M24 |
| 46 | DISPO_HSYNC | O | LCD Horizontal Sync | GPIO4[18] | AD29 |

| J3 | | | | | | |
|-------|--------------|-------|---------------------------|-----------|------------|--|
| Pin # | Pin Name | Type | Pin Group | GPIO | i.MX6 Ball | |
| 47 | CSI1_DATA14 | I | Camera Parallel Interface | GPIO2[19] | R28 | |
| 48 | ENET_MDC | O | Gigabit Ethernet | GPIO1[31] | AJ21 | |
| 49 | CSI1_DATA6 | I | Camera Parallel Interface | GPIO3[3] | AB29 | |
| 50 | ENET_MDIO | IO | Gigabit Ethernet | GPIO1[22] | AJ22 | |
| 51 | CSI1_DATA7 | I | Camera Parallel Interface | GPIO3[2] | W29 | |
| 52 | ENET_REF_CLK | I | Gigabit Ethernet | GPIO1[23] | AH21 | |
| 53 | GND | POWER | Digital GND | | | |
| 54 | GND | POWER | Digital GND | | | |
| 55 | DISPO_DAT12 | O | LCD Data | GPIO5[6] | AF28 | |
| 56 | DISPO_DAT0 | O | LCD Data | GPIO4[21] | AH29 | |
| 57 | DISPO_DAT13 | O | LCD Data | GPIO5[7] | AJ25 | |
| 58 | DISPO_DAT1 | | LCD Data | GPIO4[22] | AD27 | |
| 59 | DISPO_DAT14 | IO | LCD Data | GPIO5[8] | AJ28 | |
| 60 | DISPO_DAT2 | IO | LCD Data | GPIO4[23] | AB27 | |
| 61 | DISPO_DAT15 | IO | LCD Data | GPIO5[9] | AH25 | |
| 62 | DISPO_DAT3 | IO | LCD Data | GPIO4[24] | V23 | |
| 63 | DISPO_DAT16 | IO | LCD Data | GPIO5[10] | AB24 | |
| 64 | DISPO_DAT4 | IO | LCD Data | GPIO4[25] | V24 | |
| 65 | DISPO_DAT17 | IO | LCD Data | GPIO5[11] | AH28 | |
| 66 | DISPO_DAT5 | IO | LCD Data | GPIO4[26] | AH27 | |
| 67 | GND | POWER | Digital GND | | | |
| 68 | DISPO_CLK | IO | LCD Pixel clock | GPIO4[16] | AF29 | |
| 69 | DISPO_DAT18 | IO | LCD Data | GPIO5[12] | AH24 | |
| 70 | DISPO_DAT6 | IO | LCD Data | GPIO4[27] | U23 | |
| 71 | DISPO_DAT19 | IO | LCD Data | GPIO5[13] | AA24 | |
| 72 | DISPO_DAT7 | IO | LCD Data | GPIO4[28] | AE28 | |
| 73 | DISPO_DAT20 | IO | LCD Data | GPIO5[14] | AD24 | |
| 74 | DISPO_DAT8 | IO | LCD Data | GPIO4[29] | AJ26 | |
| 75 | DISPO_DAT21 | IO | LCD Data | GPIO5[15] | AC24 | |
| 76 | DISPO_DAT9 | IO | LCD Data | GPIO4[30] | AG28 | |
| 77 | DISPO_DAT22 | IO | LCD Data | GPIO5[16] | Y24 | |
| 78 | DISPO_DAT10 | IO | LCD Data | GPIO4[31] | AH26 | |
| 79 | DISPO_DAT23 | IO | LCD Data | GPIO5[17] | AJ24 | |
| 80 | DISPO_DAT11 | IO | LCD Data | GPIO5[5] | AJ27 | |

Note:

- [1] Pin is being latched at boot to determine boot sequence.
- [2] UART3 RTS- Use with OE# buffer, and enable only after SOM is powered-up. Use reference schematics as example.

3.2. SO-DIMM 200 Pin Mux

The table below summarizes the additional available functionality for each pin in the three board to board connectors.

J1:

| PIN | i.MX6 Ball | MODE 0 | MODE 1 | MODE 2 | MODE 3 | MODE 4 | MODE 5 | MODE 6 | MODE 7 |
|-----|------------|-------------------------------|-------------------------------------|------------------------------|-------------------------------|--------------------------------|----------------------|----------------------------------|----------------------------------|
| 9 | Y7 | ecspi1. ECSPI1_MISO | enet. ENET_MDIO | audmux. AUD5_RXFS | kpp. KEY_COL1 | uart5. UART5_TX_D ATA | gpio4. GPIO4_IO08 | usdhc1. SD1_VSELECT | |
| 11 | AB7 | ecspi1. ECSPI1_MOSI | enet. ENET_TX_DA TA3 | audmux. AUD5_RXD | kpp. KEY_ROW0 | uart4. UART4_RX_D ATA | gpio4. GPIO4_IO07 | dcic2. DCIC2_OUT | |
| 13 | AB6 | ecspi1. ECSPI1_SCLK | enet. ENET_RX_DA TA3 | audmux. AUD5_TXC | kpp. KEY_COL0 | uart4. UART4_TX_D ATA | gpio4. GPIO4_IO06 | dcic1. DCIC1_OUT | |
| 15 | AD7 | ecspi1. ECSPI1_SS1 | enet. ENET_RX_DA TA2 | flexcan1. FLEXCAN1_T X | kpp. KEY_COL2 | enet. ENET_MDC | gpio4. GPIO4_IO10 | usb. USB_H1_PWR R_CTL_WAKE | |
| 18 | AF1 | flexcan2. FLEXCAN2_T X | ipu1. IPU1_SISG4 | usb. USB_OTG_O C | kpp. KEY_COL4 | uart5. UART5_RTS_B | gpio4. GPIO4_IO14 | | |
| 20 | AC7 | flexcan2. FLEXCAN2_R X | ipu1. IPU1_SISG5 | usb. USB_OTG_P WR | kpp. KEY_ROW4 | uart5. UART5_CTS_B | gpio4. GPIO4_IO15 | | |
| 21 | AC1 | esai. ESAI_TX4_RX 1 | ecspi5. ECSPI5_RDY | epit1. EPIT1_OUT | flexcan1. FLEXCAN1_T X | uart2. UART2_TX_D ATA | gpio1. GPIO1_IO07 | spdif. SPDIF_LOCK | usb. USB_OTG_HOST_ MODE |
| 23 | V7 | esai. ESAI_TX5_RX 0 | xtalosc. XTALOSC_RE F_CLK_32K | epit2. EPIT2_OUT | flexcan1. FLEXCAN1_R X | uart2. UART2_RX_D ATA | gpio1. GPIO1_IO08 | spdif. SPDIF_SR_CL K | usb. USB_OTG_PWR_C TL_WAKE |
| 25 | AG24 | | enet. ENET_TX_EN | esai. ESAI_TX3_RX 2 | | | gpio1. GPIO1_IO28 | | |
| 36 | J23 | eim. EIM_DATA20 | ecspi4. ECSPI4_SSO | ipu1. IPU1_DIO_PI N16 | ipu2. IPU2_CSI1 _DATA15 | uart1. UART1_RTS_B | gpio3. GPIO3_IO20 | epit2. EPIT2_OUT | |
| 37 | K27 | eim. EIM_EB3 | ecspi4. ECSPI4_RDY | uart3. UART3_RTS_B | uart1. UART1_RI_B | ipu2. IPU2_CSI1_H SYNC | gpio2. GPIO2_IO31 | ipu1. IPU1_DI1_PI N03 | src. SRC_BOOT_CFG31 |
| 38 | J29 | eim. EIM_DATA19 | ecspi1. ECSPI1_SS1 | ipu1. IPU1_DIO_PI N08 | ipu2. IPU2_CSI1 _DATA16 | uart1. UART1_CTS_B | gpio3. GPIO3_IO19 | epit1. EPIT1_OUT | |
| 39 | K24 | eim. EIM_DATA23 | ipu1. IPU1_DIO_D0 _CS | uart3. UART3_CTS_B | uart1. UART1_DC_B | ipu2. IPU2_CSI1_D ATA_EN | gpio3. GPIO3_IO23 | ipu1. IPU1_DI1_PI N02 | ipu1. IPU1_DI1_PIN14 |
| 40 | V1 | ipu1. IPU1_CSI0_D ATA11 | audmux. AUD3_RXFS | ecspi2. ECSPI2_SSO | uart1. UART1_RX _DATA | | gpio5. GPIO5_IO29 | | arm. ARM_TRACE08 |
| 41 | L28 | eim. EIM_DATA25 | ecspi4. ECSPI4_SS3 | uart3. UART3_RX_D ATA | ecspi1. ECSPI1_SS 3 | ecspi2. ECSPI2_SS3 | gpio3. GPIO3_IO25 | audmux. AUD5_RXC | uart1. UART1_DSR_B |
| 42 | W3 | ipu1. IPU1_CSI0_D ATA10 | audmux. AUD3_RXC | ecspi2. ECSPI2_MISO | uart1. UART1_TX _DATA | | gpio5. GPIO5_IO28 | | arm. ARM_TRACE07 |
| 43 | L29 | eim. EIM_DATA24 | ecspi4. ECSPI4_SS2 | uart3. UART3_TX_D ATA | ecspi1. ECSPI1_SS 2 | ecspi2. ECSPI2_SS2 | gpio3. GPIO3_IO24 | audmux. AUD5_RXFS | uart1. UART1_DTR_B |
| 44 | AF2 | ecspi1. ECSPI1_SS2 | enet. ENET_TX_DA TA2 | flexcan1. FLEXCAN1_R X | kpp. KEY_ROW2 | usdhc2. SD2_VSELECT | gpio4. GPIO4_IO11 | hdmi. HDMI_TX_CE C_LINE | |
| 45 | AC6 | esai. ESAI_TX_CLK | | i2c3. I2C3_SDA | | | gpio1.GPIO1_I O06 | usdhc2. SD2_LCTL | mlb. MLB_SIG |
| 46 | AG23 | | enet. ENET_RX_EN | EsaI ESAI_TX_CLK | spdif. SPDIF_EXT _CLK | | gpio1. GPIO1_IO25 | | |
| 47 | AA6 | esai. ESAI_RX_CLK | wdog2. WDOG2_B | kpp. KEY_ROW5 | usb. USB_OTG_ID | pwm2. PWM2_OUT | gpio1. GPIO1_IO01 | usdhc1. SD1_CD_B | |

J2:

| PIN | i.MX6 Ball | MODE 0 | MODE 1 | MODE 2 | MODE 3 | MODE 4 | MODE 5 | MODE 6 | MODE 7 |
|-----|------------|-------------------------------|----------------------------------|-----------------------------|-------------------------------------|---------------------------------------|----------------------|------------------------|---------------------|
| 13 | Y6 | esai. ESAI_TX_HF_ CLK | | kpp. KEY_COL7 | | | gpio1. GPIO1_IO04 | usdhc2. SD2_CD_B | |
| 18 | N29 | eim. EIM_DATA30 | ipu1. IPU1_DISP1_ DATA21 | ipu1. IPU1_DIO_PI N11 | ipu1. IPU1_CSI0_ DATA03 | uart3. UART3_CTS _B | gpio3. GPIO3_IO30 | usb. USB_H1_OC | |
| 38 | AD22 | usb. USB_OTG_ID | enet. ENET_RX_ER | esai. ESAI_RX_HF_ CLK | spdif. SPDIF_IN | enet. ENET_1588 _EVENT2_O UT | gpio1. GPIO1_IO24 | | |
| 41 | AD3 | ecspi1. ECSPI1_SS0 | enet. ENET_COL | audmux. AUD5_RXD | kpp. KEY_ROW1 | uart5. UART5_RX_ DATA | gpio4. GPIO4_IO09 | usdhc2. SD2_VSELECT | |
| 45 | W2 | ipu1. IPU1_CSI0_D ATA08 | eim. EIM_DATA06 | ecspi2. ECSPI2_SCLK | kpp. KEY_COL7 | i2c1. I2C1_SDA | gpio5. GPIO5_IO26 | | arm. ARM_TRACE05 |
| 47 | W1 | ipu1. IPU1_CSI0_D ATA09 | eim. EIM_DATA07 | ecspi2. ECSPI2_MOS I | kpp. KEY_ROW7 | i2c1. I2C1_SCL | gpio5. GPIO5_IO27 | | arm. ARM_TRACE06 |
| 49 | AB2 | esai. ESAI_TX3_RX 2 | enet. ENET_1588_ EVENT2_IN | enet. ENET_REF_C LK | usdhc1. SD1_LCTL | spdif. SPDIF_IN | gpio7. GPIO7_IO11 | i2c3. I2C3_SDA | sjc. JTAG_DE_B |
| 51 | AB3 | Esai ESAI_TX2_RX 3 | | kpp. KEY_ROW7 | ccm. CCM_CLKO1 | | gpio1. GPIO1_IO05 | i2c3. I2C3_SCL | arm. ARM_EVENT1 |
| 55 | AE1 | esai. ESAI_RX_HF_ CLK | | i2c3. I2C3_SCL | xtalosc. XTALOSC_RE F_CLK_24M | ccm. CCM_CLKO 2 | gpio1. GPIO1_IO03 | usb. USB_H1_OC | mlb. MLB_CLK |

J3:

| PIN | i.MX6 Ball | MODE 0 | MODE 1 | MODE 2 | MODE 3 | MODE 4 | MODE 5 | MODE 6 | MODE 7 |
|-----|------------|---------------------------|----------------------------|----------------------------|---------------------------|---------------------|----------------------|---------------------|---------------------------------|
| 1 | C29 | usb. USB_H2_DAT_A | enet. RGMII_TXC | spdif. SPDIF_EXT_CLK | | | gpio6. GPIO6_IO19 | | xtalosc. XTALOSC_REF_CLK_24M |
| 2 | H24 | usb. USB_H3_STR_OBE | enet. RGMII_RXC | | | | gpio6. GPIO6_IO30 | | |
| 3 | G28 | usb. USB_H2_STR_OBE | enet. RGMII_TX_CTL | | | | gpio6. GPIO6_IO26 | | enet. ENET_REF_CLK |
| 4 | F28 | usb.USB_H3_DATA | enet. RGMII_RX_CTL | | | | gpio6. GPIO6_IO24 | | |
| 5 | C28 | mipi_hsi. HSI_TX_READY | enet. RGMII_TD0 | | | | gpio6. GPIO6_IO20 | | |
| 6 | G27 | mipi_hsi. HSI_RX_READY | enet. RGMII_RD0 | | | | gpio6. GPIO6_IO25 | | |
| 7 | E29 | mipi_hsi. HSI_RX_FLAG | enet. RGMII_TD1 | | | | gpio6. GPIO6_IO21 | | |
| 8 | F29 | mipi_hsi. HSI_TX_FLAG | enet. RGMII_RD1 | | | | gpio6. GPIO6_IO27 | | |
| 9 | G24 | mipi_hsi. HSI_RX_DATA | enet. RGMII_TD2 | | | | gpio6. GPIO6_IO22 | | |
| 10 | H23 | mipi_hsi. HSI_TX_DATA | enet. RGMII_RD2 | | | | gpio6. GPIO6_IO28 | | |
| 11 | F27 | mipi_hsi. HSI_RX_WAKE | enet. RGMII_TD3 | | | | gpio6. GPIO6_IO23 | | |
| 12 | G29 | mipi_hsi. HSI_TX_WAKE | enet. RGMII_RD3 | | | | gpio6. GPIO6_IO29 | | |
| 15 | Y28 | eim. EIM_AD10 | ipu1. IPU1_DI1_PI_N15 | ipu2. IPU2_CSI1_DATA_EN | | | gpio3. GPIO3_IO10 | | src. SRC_BOOT_CFG10 |
| 16 | E28 | usdhc2. SD2_CLK | ecspi5. ECSPI5_SCLK | kpp. KEY_COL5 | audmux. AUD4_RXFS | | gpio1. GPIO1_IO10 | | |
| 17 | AE29 | eim. EIM_AD11 | ipu1. IPU1_DI1_PI_N02 | ipu2. IPU2_CSI1_HSYNC | | | gpio3. GPIO3_IO11 | | src. SRC_BOOT_CFG11 |
| 18 | B29 | usdhc2. SD2_DATA0 | ecspi5. ECSPI5_MISO | | audmux. AUD4_RXD | kpp. KEY_ROW7 | gpio1. GPIO1_IO15 | dcic2. DCIC2_OUT | |
| 19 | Y27 | eim. EIM_AD12 | ipu1. IPU1_DI1_PI_N03 | ipu2. IPU2_CSI1_VSYNC | | | gpio3. GPIO3_IO12 | | src. SRC_BOOT_CFG12 |
| 20 | D29 | usdhc2. SD2_CMD | ecspi5. ECSPI5_MOSI | kpp. KEY_ROW5 | audmux. AUD4_RXC | | gpio1. GPIO1_IO11 | | |
| 21 | T29 | eim. EIM_ADDR16 | ipu1. IPU1_DI1_DSP_CLK | ipu2. IPU2_CSI1_PIXCLK | | | gpio2. GPIO2_IO22 | | src. SRC_BOOT_CFG16 |
| 22 | B28 | usdhc2. SD2_DATA2 | ecspi5. ECSPI5_SS1 | eim. EIM_CS3 | audmux. AUD4_TXD | kpp. KEY_ROW6 | gpio1. GPIO1_IO13 | | |
| 23 | W28 | eim. EIM_AD05 | ipu1. IPU1_DISP1_DATA04 | ipu2. IPU2_CSI1_DATA04 | | | gpio3. GPIO3_IO05 | | src. SRC_BOOT_CFG05 |
| 24 | F24 | usdhc2. SD2_DATA1 | ecspi5. ECSPI5_SS0 | eim. EIM_CS2 | audmux. AUD4_TXFS | kpp. KEY_COL7 | gpio1. GPIO1_IO14 | | |
| 25 | W27 | eim. EIM_AD04 | ipu1. IPU1_DISP1_DATA05 | ipu2. IPU2_CSI1_DATA05 | | | gpio3. GPIO3_IO04 | | src. SRC_BOOT_CFG04 |
| 26 | F23 | usdhc2. SD2_DATA3 | ecspi5. ECSPI5_SS3 | kpp. KEY_COL6 | audmux. AUD4_TXC | | gpio1. GPIO1_IO12 | | |
| 29 | K29 | eim. EIM_DATA21 | ecspi4. ECSPI4_SCLK | ipu1. IPU1_DIO_PI_N17 | ipu2. IPU2_CSI1_DATA11 | usb. USB_OTG_OC | gpio3. GPIO3_IO21 | i2c1. I2C1_SCL | spdif. SPDIF_IN |
| 30 | N27 | eim. EIM_ADDR24 | ipu1. IPU1_DISP1_DATA19 | ipu2. IPU2_CSI1_DATA19 | ipu1. IPU2_SISG2 | ipu1. IPU1_SISG2 | gpio5. GPIO5_IO04 | | src. SRC_BOOT_CFG24 |
| 31 | K28 | eim. EIM_DATA22 | ecspi4. ECSPI4_MISO | ipu1. IPU1_DIO_PI_N01 | ipu2. IPU2_CSI1_DATA10 | usb. USB_OTG_PWR | gpio3. GPIO3_IO22 | spdif. SPDIF_OUT | |

D A R T - M X 6 S Y S T E M O N M O D U L E

| PIN | i.MX6 Ball | MODE 0 | MODE 1 | MODE 2 | MODE 3 | MODE 4 | MODE 5 | MODE 6 | MODE 7 |
|-----|------------|--------------------------------|--------------------------------|-------------------------------|----------------------|---------------------------------------|----------------------|------------------------|------------------------|
| 32 | N28 | eim. EIM_ADDR23 | ipu1. IPU1_DISP1_ DATA18 | ipu2. IPU2_CSI1_D ATA18 | ipu2. IPU2_SISG3 | ipu1. IPU1_SISG3 | gpio6. GPIO6_IO06 | | src. SRC_BOOT_CFG23 |
| 33 | V27 | eim. EIM_AD01 | ipu1. IPU1_DISP1_ DATA08 | ipu2. IPU2_CSI1_D ATA08 | | | gpio3. GPIO3_IO01 | | src. SRC_BOOT_CFG01 |
| 34 | P28 | eim. EIM_ADDR22 | ipu1. IPU1_DISP1_ DATA17 | ipu2. IPU2_CSI1_D ATA17 | | | gpio2. GPIO2_IO16 | | src. SRC_BOOT_CFG22 |
| 35 | V28 | eim. EIM_AD00 | ipu1. IPU1_DISP1_ DATA09 | ipu2. IPU2_CSI1_D ATA09 | | | gpio3. GPIO3_IO00 | | src. SRC_BOOT_CFG00 |
| 36 | P29 | eim. EIM_ADDR21 | ipu1. IPU1_DISP1_ DATA16 | ipu2. IPU2_CSI1_D ATA16 | | | gpio2. GPIO2_IO17 | | src. SRC_BOOT_CFG21 |
| 37 | P24 | eim. EIM_EB1 | ipu1. IPU1_DISP1_ DATA10 | ipu2. IPU2_CSI1_D ATA10 | | | gpio2. GPIO2_IO29 | | src. SRC_BOOT_CFG28 |
| 38 | R29 | eim. EIM_ADDR20 | ipu1. IPU1_DISP1_ DATA15 | ipu2. IPU2_CSI1_D ATA15 | | | gpio2. GPIO2_IO18 | | src. SRC_BOOT_CFG20 |
| 41 | N23 | eim. EIM_EB0 | ipu1. IPU1_DISP1_ DATA11 | ipu2. IPU2_CSI1_D ATA11 | | ccm. CCM_PMIC _READY | gpio2. GPIO2_IO28 | | src. SRC_BOOT_CFG27 |
| 42 | W24 | ipu1. IPU1_DIO_PI N03 | ipu2. IPU2_DIO_PI N03 | audmux. AUD6_TXFS | | | gpio4. GPIO4_IO19 | | |
| 43 | N24 | eim. EIM_ADDR17 | ipu1. IPU1_DISP1_ DATA12 | ipu2.IPU2_C SI1_DATA12 | | | gpio2. GPIO2_IO21 | | src. SRC_BOOT_CFG17 |
| 44 | AD28 | ipu1. IPU1_DIO_PI N15 | ipu2. IPU2_DIO_PI N15 | audmux. AUD6_TXC | | | gpio4. GPIO4_IO17 | | |
| 45 | M24 | eim. EIM_ADDR18 | ipu1.IPU1_DI SP1_DATA13 | ipu2. IPU2_CSI1_D ATA13 | | | gpio2. GPIO2_IO20 | | src. SRC_BOOT_CFG18 |
| 46 | AD29 | ipu1. IPU1_DIO_PI N02 | ipu2. IPU2_DIO_PI N02 | audmux. AUD6_RXD | | | gpio4. GPIO4_IO18 | | |
| 47 | R28 | eim. EIM_ADDR19 | ipu1. IPU1_DISP1_ DATA14 | ipu2. IPU2_CSI1_D ATA14 | | | gpio2. GPIO2_IO19 | | src. SRC_BOOT_CFG19 |
| 48 | AJ21 | mlb. MLB_DATA | enet. ENET_MDC | esai. ESAI_TX5_R X0 | | enet. ENET_1588 _EVENT1_I N | gpio1. GPIO1_IO31 | | |
| 49 | AB29 | eim. EIM_AD03 | ipu1. IPU1_DISP1_ DATA06 | ipu2. IPU2_CSI1_D ATA06 | | | gpio3. GPIO3_IO03 | | src. SRC_BOOT_CFG03 |
| 50 | AJ22 | | enet. ENET_MDIO | Esai .ESAI_RX_CL K | | enet. ENET_1588 _EVENT1_O UT | gpio1. GPIO1_IO22 | spdif. SPDIF_LOCK | |
| 51 | W29 | eim. EIM_AD02 | ipu1. IPU1_DISP1_ DATA07 | ipu2. IPU2_CSI1_D ATA07 | | | gpio3. GPIO3_IO02 | | src. SRC_BOOT_CFG02 |
| 52 | AH21 | | enet. ENET_TX_CL K | esai. ESAI_RX_FS | | | gpio1. GPIO1_IO23 | spdif. SPDIF_SR_CLK | |
| 55 | AF28 | ipu1. IPU1_DISP0_ DATA12 | ipu2. IPU2_DISP0_ DATA12 | | | | gpio5. GPIO5_IO06 | | |
| 56 | AH29 | ipu1. IPU1_DISP0_ DATA00 | ipu2. IPU2_DISP0_ DATA00 | ecspi3. ECSPI3_SCLK | | | gpio4. GPIO4_IO21 | | |
| 57 | AJ25 | ipu1. IPU1_DISP0_ DATA13 | ipu2. IPU2_DISP0_ DATA13 | | audmux. AUD5_RXFS | | gpio5. GPIO5_IO07 | | |
| 58 | AD27 | ipu1. IPU1_DISP0_ DATA01 | ipu2. IPU2_DISP0_ DATA01 | ecspi3. ECSPI3_MOS I | | | gpio4. GPIO4_IO22 | | |
| 59 | AJ28 | ipu1. IPU1_DISP0_ DATA14 | ipu2. IPU2_DISP0_ DATA14 | | audmux. AUD5_RXC | | gpio5. GPIO5_IO08 | | |

D A R T - M X 6 S Y S T E M O N M O D U L E

| PIN | i.MX6 Ball | MODE 0 | MODE 1 | MODE 2 | MODE 3 | MODE 4 | MODE 5 | MODE 6 | MODE 7 |
|-----|------------|--------------------------------|--------------------------------|----------------------------|-----------------------|------------------------------|----------------------|--------|-----------------|
| 60 | AB27 | ipu1. IPU1_DISP0_ DATA02 | ipu2. IPU2_DISP0_ DATA02 | ecspi3. ECSPI3_MIS O | | | gpio4. GPIO4_IO23 | | |
| 61 | AH25 | ipu1. IPU1_DISP0_ DATA15 | ipu2. IPU2_DISP0_ DATA15 | ecspi1. ECSPI1_SS1 | ecspi2. ECSPI1_SS1 | | gpio5. GPIO5_IO09 | | |
| 62 | V23 | ipu1. IPU1_DISP0_ DATA03 | ipu2. IPU2_DISP0_ DATA03 | ecspi3. ECSPI3_SS0 | | | gpio4. GPIO4_IO24 | | |
| 63 | AB24 | ipu1. IPU1_DISP0_ DATA16 | ipu2. IPU2_DISP0_ DATA16 | ecspi2. ECSPI2_MOS I | audmux. AUD5_TXC | sdma. SDMA_EXT_ EVENT0 | gpio5. GPIO5_IO10 | | |
| 64 | V24 | ipu1. IPU1_DISP0_ DATA04 | ipu2. IPU2_DISP0_ DATA04 | ecspi3. ECSPI3_SS1 | | | gpio4. GPIO4_IO25 | | |
| 65 | AH28 | ipu1. IPU1_DISP0_ DATA17 | ipu2. IPU2_DISP0_ DATA17 | ecspi2. ECSPI2_MIS O | audmux. AUD5_TXD | sdma. SDMA_EXT_ EVENT1 | gpio5. GPIO5_IO11 | | |
| 66 | AH27 | ipu1. IPU1_DISP0_ DATA05 | ipu2. IPU2_DISP0_ DATA05 | ecspi3. ECSPI3_SS2 | audmux. AUD6_RXFS | | gpio4. GPIO4_IO26 | | |
| 68 | AF29 | ipu1. IPU1_DIO_DI SP_CLK | ipu2. IPU2_DIO_DI SP_CLK | | | | | | |
| 69 | AH24 | ipu1. IPU1_DISP0_ DATA18 | ipu2. IPU2_DISP0_ DATA18 | ecspi2. ECSPI2_SS0 | audmux. AUD5_TXFS | audmux. AUD4_RXFS | gpio5. GPIO5_IO12 | | eim. EIM_CS2 |
| 70 | U23 | ipu1. IPU1_DISP0_ DATA06 | ipu2. IPU2_DISP0_ DATA06 | ecspi3. ECSPI3_SS3 | audmux. AUD6_RXC | | gpio4. GPIO4_IO27 | | |
| 71 | AA24 | ipu1. IPU1_DISP0_ DATA19 | ipu2. IPU2_DISP0_ DATA19 | ecspi2. ECSPI2_SCLK | audmux. AUD5_RXD | audmux. AUD4_RXC | gpio5. GPIO5_IO13 | | eim. EIM_CS3 |
| 72 | AE28 | ipu1. IPU1_DISP0_ DATA07 | ipu2. IPU2_DISP0_ DATA07 | ecspi3. ECSPI3_RDY | | | gpio4. GPIO4_IO28 | | |
| 73 | AD24 | ipu1. IPU1_DISP0_ DATA20 | ipu2. IPU2_DISP0_ DATA20 | ecspi1. ECSPI1_SCLK | audmux. AUD4_TXC | | gpio5. GPIO5_IO14 | | |
| 74 | AJ26 | ipu1. IPU1_DISP0_ DATA08 | ipu2. IPU2_DISP0_ DATA08 | pwm1. PWM1_OUT | wdog1. WDOG1_B | | gpio4. GPIO4_IO29 | | |
| 75 | AC24 | ipu1. IPU1_DISP0_ DATA21 | ipu2. IPU2_DISP0_ DATA21 | ecspi1. ECSPI1_MOS I | audmux. AUD4_TXD | | gpio5. GPIO5_IO15 | | |
| 76 | AG28 | ipu1. IPU1_DISP0_ DATA09 | ipu2. IPU2_DISP0_ DATA09 | pwm2. PWM2_OUT | wdog2. WDOG2_B | | gpio4. GPIO4_IO30 | | |
| 77 | Y24 | ipu1. IPU1_DISP0_ DATA22 | ipu2. IPU2_DISP0_ DATA22 | ecspi1. ECSPI1_MIS O | audmux. AUD4_TXFS | | gpio5. GPIO5_IO16 | | |
| 78 | AH26 | ipu1. IPU1_DISP0_ DATA10 | ipu2. IPU2_DISP0_ DATA10 | | | | gpio4. GPIO4_IO31 | | |
| 79 | AJ24 | ipu1. IPU1_DISP0_ DATA23 | ipu2. IPU2_DISP0_ DATA23 | ecspi1. ECSPI1_SS0 | audmux. AUD4_RXD | | gpio5. GPIO5_IO17 | | |
| 80 | AJ27 | ipu1. IPU1_DISP0_ DATA11 | ipu2. IPU2_DISP0_ DATA11 | | | | gpio5. GPIO5_IO05 | | |

4. SOM's interfaces

4.1. Display Interfaces

4.1.1. Overview

The DART-MX6 consists of the following display interfaces:

- One parallel Display interface - driven directly by IPU1
- Two LVDS channels, driven by the LDB; pixel clock up to 170 MHz
- One HDMI port (ver. 1.4) - driven by the HDMI transmitter: Pixel clock up to 266 MHz (gated by the IPU capabilities)
- One MIPI/DSI port - driven by the MIPI/DSI transmitter; two data lanes @ 1 GHz
- Each IPU has two display ports. Up to four external ports can be active at any given time (additional asynchronous data flows can be sent through the parallel ports and the MIPI/DSI port).

4.1.2 Parallel Display

The parallel display interface provided by IPU1 consists of 24-bit data bus.

- Supports BT.656 (8-bit) and BT.1120 (16-bit) protocols
- Supports HDTV standards SMPTE274 (1080i/p) and SMPTE296 (720p)

Parallel Display signals:

| Signal | Pin # | Type | Description |
|---------------|-------|------|---------------------|
| DISP0_VSYNCH | J3.42 | O | LCD Vertical Sync |
| DISP0_DATA_EN | J3.44 | O | LCD Data Enable |
| DISP0_HSYNCH | J3.46 | O | LCD Horizontal Sync |
| DISP0_CLK | J3.68 | O | LCD Pixel Clock |
| DISP0_DAT0 | J3.56 | O | LCD Data Line 0 |
| DISP0_DAT1 | J3.58 | O | LCD Data Line 1 |
| DISP0_DAT2 | J3.60 | O | LCD Data Line 2 |
| DISP0_DAT3 | J3.62 | O | LCD Data Line 3 |
| DISP0_DAT4 | J3.64 | O | LCD Data Line 4 |
| DISP0_DAT5 | J3.66 | O | LCD Data Line 5 |
| DISP0_DAT6 | J3.70 | O | LCD Data Line 6 |
| DISP0_DAT7 | J3.72 | O | LCD Data Line 7 |
| DISP0_DAT8 | J3.74 | O | LCD Data Line 8 |
| DISP0_DAT9 | J3.76 | O | LCD Data Line 9 |
| DISP0_DAT10 | J3.78 | O | LCD Data Line 10 |
| DISP0_DAT11 | J3.80 | O | LCD Data Line 11 |
| DISP0_DAT12 | J3.55 | O | LCD Data Line 12 |
| DISP0_DAT13 | J3.57 | O | LCD Data Line 13 |
| DISP0_DAT14 | J3.59 | O | LCD Data Line 14 |
| DISP0_DAT15 | J3.61 | O | LCD Data Line 15 |
| DISP0_DAT16 | J3.63 | O | LCD Data Line 16 |

| | | | |
|----------------------------|-------|---|------------------|
| DISP0_DAT17 | J3.65 | O | LCD Data Line 17 |
| DISP0_DAT18 ^[1] | J3.69 | O | LCD Data Line 18 |
| DISP0_DAT19 ^[1] | J3.71 | O | LCD Data Line 19 |
| DISP0_DAT20 ^[1] | J3.73 | O | LCD Data Line 20 |
| DISP0_DAT21 ^[1] | J3.75 | O | LCD Data Line 21 |
| DISP0_DAT22 ^[1] | J3.77 | O | LCD Data Line 22 |
| DISP0_DAT23 ^[1] | J3.79 | O | LCD Data Line 23 |

Note:

[1] Pins are shared with on board with Bluetooth Audio connectivity interface.

4.1.3 DSI

DART-MX6 MIPI DSI Host Controller supports up to 2 D-PHY data lanes:

- Bidirectional communication and escape mode support through the data lane
- Programmable display resolutions, from 160 x 120(QQVGA) to 1024 x 768(XVGA)
- Multiple peripheral support capability, configurable virtual channels
- Video mode pixel formats, 16 bpp (5,6,5 RGB), 18 bpp (6,6,6,RGB) packed, 18 bpp (6,6,6,RGB) loosely, 24 bpp (8,8,8,RGB)

DSI signals:

| Signal | Pin # | Type | Description |
|-----------|-------|------|----------------------------------|
| DSI_CLK0M | J2.39 | ODS | Negative DSI clock differential |
| DSI_CLK0P | J2.37 | ODS | Positive DSI clock differential |
| DSI_D0M | J2.35 | ODS | Negative DSI data 0 differential |
| DSI_D0P | J2.33 | ODS | Positive DSI data 0 differential |
| DSI_D1M | J2.34 | ODS | Negative DSI data 1 differential |
| DSI_D1P | J2.36 | ODS | Positive DSI data 1 differential |

4.1.4 HDMI

The HDMI module provides an HDMI standard interface port to an HDMI 1.4 compliant display

HDMI Signals:

| Signal | Pin # | Type | Description |
|-------------|-------|------|-----------------------------------|
| HDMI_CLKM | J2.30 | ODS | Negative HDMI clock differential |
| HDMI_CLKP | J2.28 | ODS | Positive HDMI clock differential |
| HDMI_D0M | J2.46 | ODS | Negative HDMI data 0 differential |
| HDMI_D0P | J2.44 | ODS | Positive HDMI data 0 differential |
| HDMI_D1M | J2.50 | ODS | Negative HDMI data 1 differential |
| HDMI_D1P | J2.48 | ODS | Positive HDMI data 1 differential |
| HDMI_D2M | J2.56 | ODS | Negative HDMI data 2 differential |
| HDMI_D2P | J2.54 | ODS | Positive HDMI data 2 differential |
| HDMI_DDCCEC | J1.16 | IO | One wire bidirectional CEC |
| HDMI_HPD | J1.22 | I | Hot plug detect |

4.1.5 LVDS Interface

LVDS Display Bridge (LDB) will be used to connect the IPU (Image Processing Unit) to the External LVDS display interface.

There are 2 LVDS channels. These outputs are used to communicate RGB data and controls to external LCD displays.

The LVDS ports may be used as follows:

- Single channel output
- Dual channel output (one input source, two channel outputs for two displays)
- Split channel output (one input source, split to two channels on output)
- Separate two channel output (two input sources from IPU)

LVDS0 Signals:

| Signal | Pin # | Type | Description |
|-------------|-------|------|------------------------------|
| LVDS0_TX0_N | J2.57 | ODS | Negative data 0 differential |
| LVDS0_TX0_P | J2.59 | ODS | Positive data 0 differential |
| LVDS0_TX1_N | J2.61 | ODS | Negative data 1 differential |
| LVDS0_TX1_P | J2.63 | ODS | Positive data 1 differential |
| LVDS0_TX2_N | J2.65 | ODS | Negative data 2 differential |
| LVDS0_TX2_P | J2.67 | ODS | Positive data 2 differential |
| LVDS0_TX3_N | J2.71 | ODS | Negative data 3 differential |
| LVDS0_TX3_P | J2.73 | ODS | Positive data 3 differential |
| LVDS0_CLK_N | J2.75 | ODS | Negative clock differential |
| LVDS0_CLK_P | J2.77 | ODS | Positive clock differential |

LVDS1 Signals:

| Signal | Pin # | Type | Description |
|-------------|-------|------|------------------------------|
| LVDS1_TX0_N | J2.58 | ODS | Negative data 0 differential |
| LVDS1_TX0_P | J2.60 | ODS | Positive data 0 differential |
| LVDS1_TX1_N | J2.62 | ODS | Negative data 1 differential |
| LVDS1_TX1_P | J2.64 | ODS | Positive data 1 differential |
| LVDS1_TX2_N | J2.66 | ODS | Negative data 2 differential |
| LVDS1_TX2_P | J2.68 | ODS | Positive data 2 differential |
| LVDS1_TX3_N | J2.72 | ODS | Negative data 3 differential |
| LVDS1_TX3_P | J2.74 | ODS | Positive data 3 differential |
| LVDS1_CLK_N | J2.76 | ODS | Negative clock differential |
| LVDS1_CLK_P | J2.78 | ODS | Positive clock differential |

4.2. Camera Interfaces

4.2.1. MIPI CSI-2

The CSI-2 Host Controller is a digital core that implements all protocol functions defined in the MIPI CSI-2 specification, providing an interface between the system and the MIPI D-PHY, allowing communication with an MIPI CSI-2 compliant camera sensor.

The MIPI CSI-2 host controller supports the following features:

- Compliance with MIPI Alliance standard for camera serial interface 2 (CSI-2), version 1.00 29th November, 2005
- Optional support for Camera Control Interface (CCI) through the use of DesignWare Core (DW_apb_i2c)
- Interface with MIPI D-PHY following PHY Protocol Interface (PPI), as defined in MIPI Alliance Specification for D-PHY, version 1.00.00 14th May, 2009
- Supports up to 4 D-PHY Rx data lanes
- Dynamically configurable multi-lane merging
- Long and short packet decoding
- Timing accurate signaling of frame and line synchronization packets
- Support for several frame formats such as:
 - General frame or digital interlaced video with or without accurate sync timing
 - Data type (packet or frame level) and virtual channel interleaving
- 32-bit image data interface delivering data formatted as recommended in CSI-2 specification
- Supports all primary and secondary data formats:
 - RGB, YUV and RAW color space definitions
 - From 24-bit down to 6-bit per pixel
 - Generic or user-defined byte-based data types
 - Error detection and correction:
 - PHY level
 - Packet level
 - Line level
 - Frame level

MIPI CSI-2 signals:

| Signal | Pin # | Type | Description |
|-----------|-------|------|------------------------------------|
| CSI_CLK0M | J2.10 | IDS | Negative CSI-2 clock differential |
| CSI_CLK0P | J2.8 | IDS | Positive CSI-2 clock differential |
| CSI_D0M | J2.3 | IDS | Negative CSI-2 data 0 differential |
| CSI_D0P | J2.1 | IDS | Positive CSI-2 data 0 differential |
| CSI_D1M | J2.5 | IDS | Negative CSI-2 data 1 differential |
| CSI_D1P | J2.7 | IDS | Positive CSI-2 data 1 differential |
| CSI_D2M | J2.11 | IDS | Negative CSI-2 data 2 differential |
| CSI_D2P | J2.9 | IDS | Positive CSI-2 data 2 differential |
| CSI_D3M | J2.4 | IDS | Negative CSI-2 data 3 differential |
| CSI_D3P | J2.6 | IDS | Positive CSI-2 data 3 differential |

4.2.2. Parallel CSIx

Based on i.MX6 IPU, the DART-MX6 supports a camera port controlled by IPU2 CSI1 sub-block, providing a connection to image sensors and related devices.

CSI1 Signals:

| Signal | Pin # | Type | Description |
|-------------------------------|-------|------|------------------------|
| CSI1_DATA4/ BT_CFG1_5 [1] | J3.23 | I | Camera data line |
| CSI1_DATA5 | J3.25 | I | Camera data line |
| CSI1_DATA6 | J3.49 | I | Camera data line |
| CSI1_DATA7 | J3.51 | I | Camera data line |
| CSI1_DATA8 | J3.33 | I | Camera data line |
| CSI1_DATA9 | J3.35 | I | Camera data line |
| CSI1_DATA10 | J3.37 | I | Camera data line |
| CSI1_DATA11 | J3.41 | I | Camera data line |
| CSI1_DATA12 | J3.43 | I | Camera data line |
| CSI1_DATA13 | J3.45 | I | Camera data line |
| CSI1_DATA14 | J3.47 | I | Camera data line |
| CSI1_DATA15 | J3.38 | I | Camera data line |
| CSI1_DATA16 | J3.36 | I | Camera data line |
| CSI1_DATA17 | J3.34 | I | Camera data line |
| CSI1_DATA18 | J3.32 | I | Camera data line |
| CSI1_DATA19 | J3.30 | I | Camera data line |
| CSI1_DATA_EN | J3.15 | I | Camera data enable |
| CSI1_HSYNCH/ BT_CFG2_3 [1] | J3.17 | I | Camera horizontal sync |
| CSI1_PIXCLK | J3.21 | I | Camera pixel clock |
| CSI1_VSYNC/ BT_CFG2_4 [1] | J3.19 | I | Camera vertical sync |

Note:

[1] Pin is being latched at boot to determine boot sequence. Please refer to boot options section.

4.3. Gigabit Ethernet

Gigabit Ethernet Features:

The Ethernet Media Access Controller (MAC) is designed to support 10/100/1000 Mbps Ethernet/IEEE 802.3 networks. An external Gigabit PHY Microsemi's KSZ9031RNXCA and magnetics is used on carrier board to complete the interface to the media. The i.MX6 processor also consists of HW assist for IEEE1588 standard. See the IEEE1588 section for more details.

| Signal | Pin # | Type | Description |
|------------|-------|------|---------------------------|
| RGMII_RCLK | J3.2 | I | RGMII Receive Clock |
| RGMII_RCTL | J3.4 | I | RGMII Receive Control |
| RGMII_RD0 | J3.6 | I | RGMII Receive Data Bit 0 |
| RGMII_RD1 | J3.8 | I | RGMII Receive Data Bit 1 |
| RGMII_RD2 | J3.10 | I | RGMII Receive Data Bit 2 |
| RGMII_RD3 | J3.12 | I | RGMII Receive Data Bit 3 |
| RGMII_TCLK | J3.1 | O | RGMII Transmit Clock |
| RGMII_TCTL | J3.3 | O | RGMII Transmit Control |
| RGMII_TD0 | J3.5 | O | RGMII Transmit Data Bit 0 |
| RGMII_TD1 | J3.7 | O | RGMII Transmit Data Bit 1 |
| RGMII_TD2 | J3.9 | O | RGMII Transmit Data Bit 2 |
| RGMII_TD3 | J3.11 | O | RGMII Transmit Data Bit 3 |

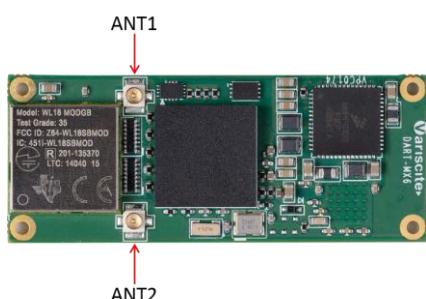
4.4. Wi-Fi & Bluetooth

The DART-MX6 contains TI's WL183xMOD WiLink, a high performance 2.4/5 GHz IEEE 802.11 a/b/g/n Bluetooth 4.0/BLE radio module with optional Dual Band and MIMO support. The modules support improved performance over WiFi in bit rates reaching 100Mbps (UDP) and 80Mbps (TCP).

The module realizes the necessary PHY/MAC layers to support WLAN applications in conjunction with a host processor over a SDIO interface.

The module also provides a Bluetooth platform through the HCI transport layer. Both WLAN and Bluetooth share the same antenna port.

- IEEE 802.11 b,g,n or Dual Band 2.4/5GHz 802.11 a/b/g/n with optional MIMO
- Bluetooth 4.0/BLE
- U.FL connectors for external antennas
- Integrated band-pass filter
- Operating Temperature Range:
Dual Band 2.4/5GHz Modules: -40 to +85
2.4GHz Modules: -20 to +70



4.5. USB Host 2.0

The USB controller block provides high performance USB functionality that conforms to the USB 2.0 specification.

USB Host1 Signals:

| Signal | Pin # | Type | Description |
|-------------|-------|------|---|
| USB_HOST_DP | J2.24 | IODS | Positive USB host data |
| USB_HOST_DN | J2.22 | IODS | Negative USB host data |
| USB_H1_VBUS | J2.12 | I | USB 2.0 VBUS indicator (5V) |
| USB_H1_OC | J2.18 | I | USB host over current indicator , Active low 3.3v digital |

4.6. USB 2.0 OTG

USB 2.0 On-the-go Features:

High-speed OTG core

- HS/FS/LS UTMI compliant interface
- High speed, full speed and low speed operation in host mode (with UTMI transceiver)
- High speed, and full speed operation in peripheral mode (with UTMI transceiver)
- Hardware support for OTG signaling, session request protocol, and host negotiation protocol
- Up to 8 bidirectional endpoints
- Integrated HS USB PHY

OTG Signals:

| Signal | Pin # | Type | Description |
|--------------|-------|------|---|
| USB_OTG_DN | J2.27 | IODS | Negative USB OTG data |
| USB_OTG_DP | J2.29 | IODS | Positive USB OTG data |
| USB_OTG_VBUS | J2.14 | I | USB 2.0 OTG VBUS indicator (5V) |
| USB_OTG_ID | J2.38 | I | USB OTG host/client ID Low : Host mode Float: Client mode |

4.7. MMC/SD/SDIO

MX6 MMC interface features:

- Fully compliant with MMC command/response sets and physical layer as defined in the Multimedia Card System specification v4.2/4.3/4.4, including high-capacity (size > 2 GB) cards HC MMC.
- Fully compliant with SD command/response sets and physical layer as defined in the SD Memory Card specifications v3.0, including high-capacity SDHC cards up to 32 GB
- Fully compliant with SDIO command/response sets and interrupt/read-wait mode as defined in the SDIO Card specification, Part E1 v1.10
- Fully compliant with SD Card specification, Part A2, SD Host Controller Standard specification v2.00
- 1-bit or 4-bit transfer mode specifications for SD and SDIO cards up to UHS-I SDR104 mode (104 MB/s max)

- 1-bit, 4-bit, or 8-bit transfer mode specifications for MMC cards up to 52 MHz in both SDR and DDR modes (104 MB/s max). However, the SoC level integration and I/O muxing logic restrict functionality to the following:

SDMMC2 Signals:

| Signal | Pin # | Type | Description |
|-----------|-------|------|--|
| SD2_CLK | J3.16 | O | Clock for MMC/SD/SDIO card |
| SD2_CMD | J3.20 | O | CMD line connect to card |
| SD2_DATA0 | J3.18 | IO | DAT0 line in all modes (also used to detect busy state) |
| SD2_DATA1 | J3.24 | IO | DAT1 line-in |
| SD2_DATA2 | J3.22 | IO | DAT2 line |
| SD2_DATA3 | J3.26 | IO | DAT3 line-in |

4.8. Audio

The DART-MX6 features three audio interfaces:

- TLV320AIC3106 Audio codec interfaces
 1. Analog outputs / inputs:
 - stereo line-in
 - Stereo HP out
 2. Digital microphone input
- SSI Digital audio interface
- S/PDIF in/out

Analog audio signals are featured by the on-SOM TLV320AIC3106 audio codec. Refer to the data sheet for detailed electrical characteristics of the relevant interfaces

<http://www.ti.com/product/tlv320aic3106>.

Analog Signals:

| Signal | Pin # | Type | Description |
|------------|-------|------|------------------------|
| HPOUT | J1.1 | AO | Headphones out - left |
| HPROUT | J1.3 | AO | Headphones out - right |
| LINEIN1_RP | J1.4 | AI | Line-in - Right |
| LINEIN1_LP | J1.6 | AI | Line-in - Left |

Digital AUDMUX:

Key features of the block include:

- Full 6-wire SSI interfaces for asynchronous receive and transmit
- Configurable 4-wire (synchronous) or 6-wire (asynchronous) peripheral interfaces
- Independent Tx/Rx frame sync and clock direction selection for host or peripheral
- Each host interface's capability to connect to any other host or peripheral interface in a point-to-point or point-to-multipoint (network mode)
- Transmit and receive data switching to support external network mode

AUDMUX4 Signals:

| Signal | Pin # | Type | Description |
|-----------------------------|-------|------|---|
| AUDMUX4_TXD ^[1] | J3.75 | IO | Transmit data from pin |
| AUDMUX4_RXD ^[1] | J3.79 | IO | Receive data at pin |
| AUDMUX4_TXC ^[1] | J3.73 | IO | Transmit clock input/output at pin |
| AUDMUX4_RXC ^[1] | J3.71 | IO | Receive clock input/output at pin |
| AUDMUX4_TXFS ^[1] | J3.77 | IO | Transmit frame sync input/output at pin |
| AUDMUX4_RXFS ^[1] | J3.69 | IO | Receive frame sync input/output at pin |

Note:

[1] AUDMUX4 Signals are shared with the on-som Bluetooth Audio Interface and LCD lines. Refer to Parallel Display chapter for more details

S/PDIF (Sony Phillips Digital Interface) In/Out:

S/PDIF is a standard audio file transfer format, developed jointly by the Sony and Phillips corporations.

SPIDF Signals:

| Signal | Pin # | Type | Description |
|---------------|--|------|-----------------------|
| SPDIFIN | J3.29, J2.38 (MUXED), J2.49(MUXED) | I | In |
| SPDIFOUT | J3.31 | O | Out |
| Spdif.lock | J1.21(MUXED), J3.50(MUXED) | O | Lock signal |
| Spdif.srclk | J1.23(MUXED), J3.52(MUXED), | O | SR Lock signal |
| SPDIF_EXT_CLK | J1.46 (MUXED), J3.1 (MUXED) | I | External clock signal |

4.9. UART Interfaces

By default four UART interfaces are supported, refer to Table 3.2 for further configurations the UART interface.

UART Features:

Each of the UART modules support the following serial data transmit/receive protocols and configurations:

- 7 or 8-bit data words, one or two stop bits, programmable parity (even, odd or none)
- Programmable baud rates up to 4 MHz This is a higher max baud rate relative to the 1.875 MHz, which is stated by the TIA/EIA-232-F standard and the i.MX31 UART modules.
- 32-byte FIFO on Tx and 32 half-word FIFO on Rx supporting auto-baud
- IrDA 1.0 support (up to SIR speed of 115200 bps)

UART1 Signals:

| Signal | Pin # | Type | Description |
|-----------|-------|------|--------------------------|
| UART1_TXD | J1.42 | O | UART transmit |
| UART1_RXD | J1.40 | I | UART receive |
| UART1_RTS | J1.36 | I | UART HW flow control RTS |
| UART1_CTS | J1.38 | O | UART HW flow control CTS |

Note: UART1 is used as default boot debug port.

UART3 Signals:

| Signal | Pin # | Type | Description |
|--------------------------|------------------------|------|--------------------------|
| UART3_TXD | J1.43 | O | UART transmit |
| UART3_RXD | J1.41 | I | UART receive |
| UART3_RTS ^[1] | J1.37 | I | UART HW flow control RTS |
| UART3_CTS | J1.39, J2.18(MUXED) | O | UART HW flow control CTS |

Note:

[1] UART3 RTS pin is being latched at boot to determine boot sequence. Use with OE# buffer, and enable only after SOM is powered-up. Use reference schematics as example.

UART4 Signals:

| Signal | Pin # | Type | Description |
|-----------|--------------|------|---------------|
| UART4_TXD | J1.13(MUXED) | O | UART transmit |
| UART4_RXD | J1.11(MUXED) | I | UART receive |

UART5 Signals:

| Signal | Pin # | Type | Description |
|-----------|--------------|------|--------------------------|
| UART5_TXD | J1.9(MUXED) | O | UART transmit |
| UART5_RXD | J2.41(MUXED) | I | UART receive |
| UART5_RTS | J1.18(MUXED) | I | UART HW flow control RTS |
| UART5_CTS | J1.20(MUXED) | O | UART HW flow control CTS |

4.10. Flexible Controller Area Network (FLEXCAN)

The CAN protocol was primarily, but not exclusively, designed to be used as a vehicle serial data bus, meeting the specific requirements of this field: Real-time processing, reliable operation in the Electromagnetic Interference (EMI) environment of a vehicle, cost-effectiveness and required bandwidth. The FlexCAN module is a full implementation of the CAN protocol specification, version 2.0 B, which supports both standard and extended message frames.

CAN1 Signals:

| Signal | Pin # | Type | Description |
|---------|------------------------|------|------------------|
| CAN1_TX | J1.21, J1.15(MUXED) | O | CAN BUS transmit |
| CAN1_RX | J1.23, J1.44(MUXED) | I | CAN BUS receive |

CAN2 Signals:

| Signal | Pin # | Type | Description |
|---------|-------|------|------------------|
| CAN2_TX | J1.18 | O | CAN BUS transmit |
| CAN2_RX | J1.20 | I | CAN BUS receive |

Signal Descriptions

CAN Rx: The receive pin from the CAN bus transceiver. Dominant state is represented by logic level '0'. Recessive state is represented by logic level '1'.

CAN Tx: The transmit pin to the CAN bus transceiver. Dominant state is represented by logic level '0'. Recessive state is represented by logic level '1'.

4.11. SPI

The Enhanced Configurable Serial Peripheral Interface (eCSPI) is a full-duplex, synchronous 4-wire serial communication block. The eCSPI contains a 64 x 32 receive buffer (RXFIFO) and a 64 x 32 transmit buffer (TXFIFO). With data FIFOs, the eCSPI allows rapid data communication with fewer software interruptions.

4.11.1. eCSPI Key Features:

- Full-duplex synchronous serial interface
- Master/slave configurable
- Four chip select (SS) signals to support multiple peripherals
- Transfer continuation function allows unlimited length data transfers
- 32-bit wide by 64-entry FIFO for both transmitting and receiving data
- 32-bit wide by 16-entry FIFO for HT message data
- Polarity and phase of the chip select (SS) and SPI clock (SCLK) are configurable
- Direct Memory Access (DMA) support
- Max operation frequency up to the reference clock frequency

ECSPI1 Signals:

| Signal | Pin # | Type | Description |
|-------------|---|------|---------------------------|
| ECSPI1_CLK | J1.16, J3.73(MUXED) | IO | SPI1 clock |
| ECSPI1_MOSI | J1.11, J3.75(MUXED) | IO | SPI1 MOSI signal |
| ECSPI1_MISO | J1.9, J3.77(MUXED) | IO | SPI1 SOMI signal |
| ECSPI1_CS0 | J2.41, J3.79(MUXED) | IO | SPI1 chip select 0 signal |
| ECSPI1_CS1 | J1.15, J1.38(MUXED), J3.61(MUXED) | IO | SPI1 chip select 1 signal |
| ECSPI1_CS2 | J1.43(MUXED), J1.44(MUXED) | IO | SPI1 chip select 2 signal |
| ECSPI1_CS3 | J1.41 (MUXED) | IO | SPI1 chip select 3 signal |

ECSPI2 Signals:

| Signal | Pin # | Type | Description |
|-------------|-------------------------------|------|------------------|
| ECSPI2_CLK | J3.69(MUXED), J3.71(MUXED) | IO | SPI2 clock |
| ECSPI2_MOSI | J2.47(MUXED), J3.63(MUXED) | IO | SPI2 MOSI signal |
| ECSPI2_MISO | J1.42(MUXED), J3.65(MUXED) | IO | SPI2 SOMI signal |

| | | | |
|------------|----------------------------|----|---------------------------|
| ECSPI2_CS0 | J1.40(MUXED), J3.69(MUXED) | IO | SPI2 Chip select 0 signal |
| ECSPI2_CS1 | J3.61 (MUXED) | IO | SPI2 Chip select 1 signal |
| ECSPI2_CS2 | J1.43(MUXED) | IO | SPI2 Chip select 2 signal |
| ECSPI2_CS3 | J1.41(MUXED) | IO | SPI2 Chip select 3 signal |

ECSPI3 Signals:

| Signal | Pin # | Type | Description |
|-------------|--------------|------|---------------------------|
| ECSPI3_CLK | J3.56(MUXED) | IO | SPI3 clock |
| ECSPI3_MOSI | J3.58(MUXED) | IO | SPI3 MOSI signal |
| ECSPI3_MISO | J3.60(MUXED) | IO | SPI3 SOMI signal |
| ECSPI3_CS0 | J3.62(MUXED) | IO | SPI3 Chip select 0 signal |
| ECSPI3_CS1 | J3.64(MUXED) | IO | SPI3 Chip select 1 signal |
| ECSPI3_CS2 | J3.66(MUXED) | IO | SPI3 Chip select 2 signal |
| ECSPI3_CS3 | J3.70(MUXED) | IO | SPI3 Chip select 3 signal |
| ECSPI3_RDY | J3.72(MUXED) | I | SPI3 ready signal |

ECSPI5 Signals:

| Signal | Pin # | Type | Description |
|-------------|--------------|------|---------------------------|
| ECSPI5_CLK | J3.16(MUXED) | IO | SPI5 clock |
| ECSPI5_MOSI | J3.20(MUXED) | IO | SPI5 MOSI signal |
| ECSPI5_MISO | J3.18(MUXED) | IO | SPI5 SOMI signal |
| ECSPI5_CS0 | J3.24(MUXED) | IO | SPI5 Chip select 0 signal |
| ECSPI5_CS1 | J3.22(MUXED) | IO | SPI5 Chip select 1 signal |
| ECSPI5_CS3 | J3.26(MUXED) | IO | SPI5 Chip select 3 signal |
| ECSPI5_RDY | J1.21(MUXED) | I | SPI5 ready signal |

4.12. PCIe

DART-MX6 PCI Express functionality has the following parts:

PCI Express includes the following cores:

- PCI Express Dual Mode (DM) core
- PCI Express Root Complex (RC) core
- PCI Express Endpoint (EP) core

PCI Express 2.0 PHY:

- PCIe 2.0 PHY is a complete mixed-signal semiconductor intellectual property (IP) solution, designed for single-chip integration into computer applications
- The PCIe 2.0 PHY supports both the 5 Gbps data rate of the PCI Express Gen 2.0 specifications as well as being backwards compatible to the 2.5Gb/s Gen 1.1 specification

PCIE Signals:

| Signal | Pin # | Type | Description |
|----------|-------|------|---------------------------------|
| PCIE_TXP | J2.19 | DS | Positive PCI TX differential |
| PCIE_TXM | J2.21 | DS | Negative PCI TX differential |
| PCIE_RXP | J2.23 | DS | Positive PCI RX differential |
| PCIE_RXM | J2.25 | DS | Negative PCI RX differential |
| CLK1_P | J2.40 | DS | Positive PCI clock differential |
| CLK1_N | J2.42 | DS | Negative PCI clock differential |

4.13. I²C

I2C-1, 2, 3 Interface connectivity peripherals provide serial interface for external devices. Data rates of up to 400 kbps are supported.

I2C1 Signals:

| Signal | Pin # | Type | Description |
|----------|------------------------|------|---|
| I2C1_SCL | J2.47, J3.29(MUXED) | IO | I2C1 I ² C clock, open drain |
| I2C1_SDA | J2.45 | IO | I2C1 I ² C data, open drain |

I2C3 Signals:

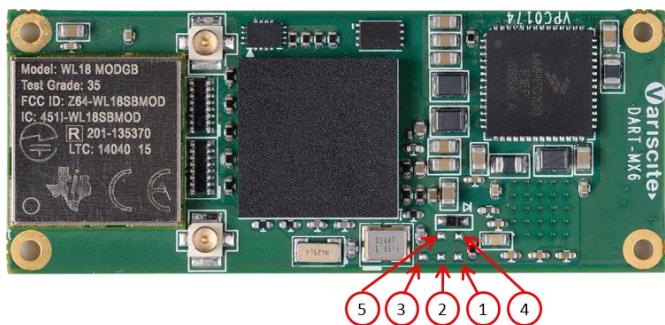
| Signal | Pin # | Type | Description |
|----------|------------------------|------|---|
| I2C3_SCL | J2.51, J2.55(MUXED) | IO | I2C3 I ² C clock, open drain |
| I2C3_SDA | J2.49, J1.45(MUXED) | IO | I2C3 I ² C data, open drain |

4.14. JTAG

The System JTAG Controller (SJC) provides debug and test control with maximum security. The test access port (TAP) is designed to support features compatible with the IEEE standard 1149.1 v2001 (JTAG). Support IEEE P1149.6 extensions to the JTAG standard are for AC testing of selected IO signals. The JTAG Interface is exported through Test Points.

JTAG signals 40-pin FFC Connector:

| Signal | TP # | Type | Description |
|------------|------|------|-----------------------|
| JTAG_TDI | 5 | I | JTAG data-in |
| JTAG_NTRST | 4 | I | JTAG reset |
| JTAG_TMS | 3 | I | JTAG test mode select |
| JTAG_TCK | 1 | O | JTAG test clock |
| JTAG_TDO | 2 | O | JTAG data-out |



4.15. General Purpose IOs

Most of the SoM's IO pins can be used as GPIOs.

Please refer to Chapter 3, for complete SoM connectors signal list and GPIO multiplexing.

4.16. General System Control

4.16.1. Boot Options

Below you can find the MX6 boot options

| 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |
|---------------------------------|-----------|-----------|-----------|--|-----------|---|-----------|
| BT_CFG1_7 | BT_CFG1_6 | BT_CFG1_5 | BT_CFG1_4 | BT_CFG2_6 | BT_CFG2_5 | BT_CFG2_4 | BT_CFG2_3 |
| 1XXX = NANDF Boot | | | | | | | |
| 011X = MMC/eMMC Boot | | | | X0 = 1-bit X1 = 4-bit 10 = 8-bit | | 01 = SD2 Boot 10 = SD3 Boot 11 = SD4 Boot | |
| 010X = SD/eSD Boot | | | | X0 = 1-bit X1 = 4-bit | | 01 = SD2 Boot 10 = SD3 Boot 11 = SD4 Boot | |
| 0011 = Serial ROM (SPINOR) Boot | | | | | | | |
| 0010 = SATA Boot | | | | | | | |

The boot-select pin configures the boot sequence of the DART-MX6:

BOOT_CFG = 01X001XX

| Pin Name | Pin Number | MX6 BOOT_CFG | Internally pulled |
|-----------------------|------------|--------------|-------------------|
| CSI1_DATA4/BT_CFG1_5 | J3.23 | BT_CFG1_5 | Pulled-up 10K |
| CSI1_VSYNC/BT_CFG2_4 | J3.19 | BT_CFG2_4 | Pulled-up 10K |
| CSI1_HSYNCH/BT_CFG2_3 | J3.17 | BT_CFG2_3 | Pulled-down 10K |

Use cases:

BOOT_CFG = 01100110 => SD3 boot, on-SOM eMMC Boot, 4 bit bus

BOOT_CFG = 01000101 => SD2 boot, on carrier SD-Card, 4 bit bus

4.16.2. Reset

'0' logic will reset DART-MX6

4.16.3. Reference Clock Out

DART-MX6 output clock (CLKO2) is controlled by the i.MX6 CCM module. Please refer to the i.MX6 user manual regarding the configuration option for this clock.

4.16.4. General System Control Signals

| Signal | Pin # | Type | Description |
|-----------------------|-------|------|-------------------------|
| CLKO | J2.55 | O | Clock out |
| CSI1_DATA4/BT_CFG1_5 | J3.23 | I | Refer to section 4.16.1 |
| CSI1_VSYNC/BT_CFG2_4 | J3.19 | I | Refer to section 4.16.1 |
| CSI1_HSYNCH/BT_CFG2_3 | J3.17 | I | Refer to section 4.16.1 |
| POR_B | J1.48 | I | Hardware reset |
| MX6_ONOFF | J1.19 | I | Power on/off |

4.17. Power

4.17.1. Power Supply

| Signal | Pin # | Type | Description |
|--------|--|----------|--|
| VBAT | J1.26, J1.27 J1.28, J1.29 J1.30, J1.31 J1.32, J1.33 | Power In | DART-MX6 Single DC-IN Supply voltage. Voltage range: 3.7 +/- 5% |

4.17.2. Ground

| Signal | Pin # | Type | Description |
|--------|--|-------|----------------|
| GND | J1.2, J1.7, J1.10, J1.17, J1.24, J1.34, J1.35, J1.49, J1.50, J2.15, J2.17, J2.20, J2.26, J2.31, J2.32, J2.43, J2.52, J2.53, J2.69, J2.70, J2.79, J2.80, J3.13, J3.14, J3.27, J3.28, J3.39, J3.40, J3.53, J3.54, J3.67 | Power | Digital ground |
| AGND | J1.5, J1.8 | Power | Analog GND |

5. Absolute Maximum Characteristics

| Power Supply | Min | Max | Unit |
|--------------------------|------|-----|------|
| Main Power Supply, DC-IN | -0.3 | 4.8 | V |

6. Operational Characteristics

6.1. Power supplies

| | Min | Typical | Max | Unit |
|--------------------------|-----|---------|-----|------|
| Main Power Supply, DC-IN | -5% | 3.7 | +5% | V |

6.2. Power Consumption

CPU usage:

| Task | SOM VBAT current draw in ma @3.7v |
|-------------------------------------|-----------------------------------|
| Idle (~10% CPU) @ 400mhz | 220mA |
| FHD Video playback | 365mA |
| 100% CPU Dhrystone test – Dual core | 400mA |
| 100% CPU Dhrystone test – Quad core | 650mA |

Additional peripherals:

| Task | SOM VBAT current draw in ma @3.7v |
|-------------------|-----------------------------------|
| WLAN transmission | ~320mA |
| Gbit Ethernet | ~410mA |

7. DC Electrical Characteristics

| Parameter | Min | Typical | Max | Unit |
|---------------------|----------------|---------|--------------|------|
| Digital 3.3V | | | | |
| V_{IH} | 0.7x VIN_3V3 | | VIN_3V3 | V |
| V_{IL} | 0 | | 0.3x VIN_3V3 | V |
| V_{OH} | VIN_3V3 - 0.15 | | | V |
| V_{OL} | | | 0.15 | V |

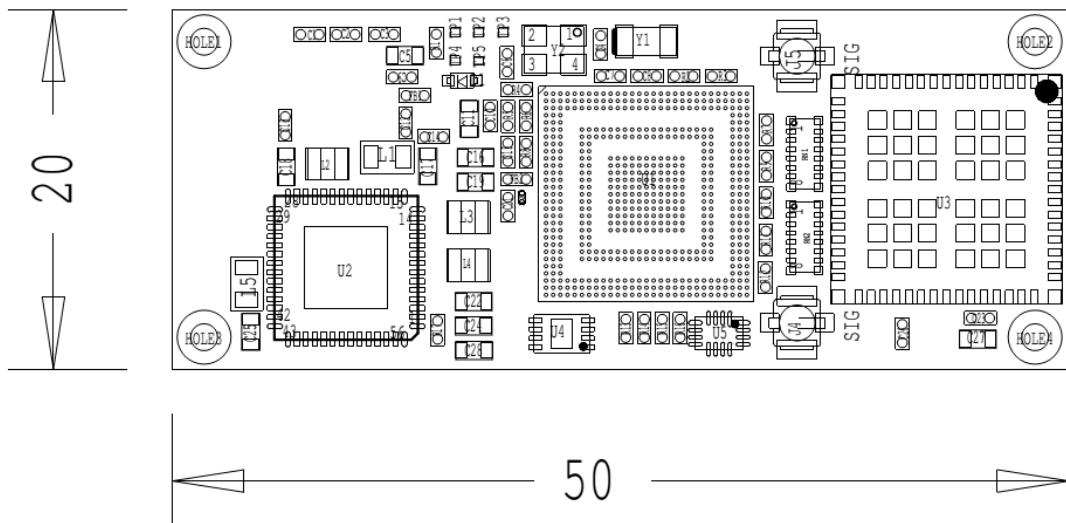
8. Environmental Specifications

| | Min | Max |
|--|---------------------------|--------|
| Commercial Operating Temperature Range | 0 °C | +70 °C |
| Extended Operating Temperature Range | -20 °C | +70 °C |
| Industrial Operating Temperature Range | -40 °C | +85 °C |
| Referring MIL-HDBK-217F-2 Parts Count Reliability Prediction Method Model: 50Deg Celsius, Class B-1, GM 50Deg Celsius, Class B-1, GB | 121 Khrs > 1400 Khrs > | |
| Shock Resistance | 50G/20 ms | |
| Vibration | 20G/0 - 600 Hz | |

Note: Extended and Industrial Temperature is only based on the operating temperature grade of the SoM components. Customer should consider specific thermal design for the final product based upon the specific environmental and operational conditions.

9. Mechanical Drawings

Top View [mm]



CAD files are available for download at <http://www.variscite.com/>

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